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# On sojourn times in $M / G I$ systems under state-dependent processor sharing 

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# On sojourn times in $M / G I$ systems under state-dependent processor sharing 

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#### Abstract

We consider a system with Poisson arrivals and i.i.d. service times. The requests are served according to the state-dependent processor sharing discipline, where each request receives a service capacity which depends on the actual number of requests in the system. The linear systems of PDEs describing the residual and attained sojourn times coincide for this system, which provides time reversibility including sojourn times for this system, and their minimal non negative solution gives the LST of the sojourn time $V(\tau)$ of a request with required service time $\tau$. For the case that the service time distribution is exponential in a neighborhood of zero, we derive a linear system of ODEs, whose minimal non negative solution gives the LST of $V(\tau)$, and which yields linear systems of ODEs for the moments of $V(\tau)$ in the considered neighborhood of zero. Numerical results are presented for the variance of $V(\tau)$. In case of an $M / G I / 2-P S$ system, the LST of $V(\tau)$ is given in terms of the solution of a convolution equation in the considered neighborhood of zero. For bounded from below service times, surprisingly simple expressions for the LST and variance of $V(\tau)$ in this neighborhood of zero are derived, which yield in particular the LST and variance of $V(\tau)$ in $M / D / 2-P S$.


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Keywords: Poisson arrivals; general service times; locally exponential service times; deterministic service times; state-dependent processor sharing; generalized processor sharing; many-server; time reversibility; insensitivity; $M / G I / r-P S ; M / D / r-P S ; M / D / 2-P S$; sojourn time; Laplace-Stieltjes transform; moments.

## 1 Introduction

Processor Sharing (PS) systems have been widely used in the last decades for modeling and analyzing computer and communication systems, cf. e.g. [Kle], [CMT], [KY], [Ya2], [BBJ], [GRZ], [YY1], [BB1], [BB2], and the references therein. In this paper we deal with sojourn times of requests in a node, where the requests are served according to the following generalized processor sharing discipline, which we call State-Dependent Processor Sharing (SDPS) discipline, cf. [Coh], [GRZ]. If there are $n \in \mathbb{N}:=\{1,2, \ldots\}$ requests in the node then each of them receives a positive service capacity $\varphi(n)$, i.e., each of the $n$ requests receives during an interval of length $\Delta \tau$ the amount $\varphi(n) \Delta \tau$ of service. In case of $\varphi_{1}(n)=1 / n, n \in \mathbb{N}$, we obtain the well known single-server PS system, cf. e.g. [CMT], [YY1], in case of $\varphi_{1, k}(n)=1 /(n+k)$, $n \in \mathbb{N}$, we have a single-server PS system with $k \in \mathbb{N}$ permanent requests in the system, cf. [YY2], [VB], in case of $\varphi_{r}(n)=\min (r / n, 1), n \in \mathbb{N}$, an $r$-server PS system, where all requests are served in a PS mode, but each request receives at most the capacity of one processor, cf. [Coh] p. 283, [Bra], [GRZ], [BB1], in case of $\varphi_{r, k}(n)=\min (r /(n+k), 1), n \in \mathbb{N}$, an $r$-server PS system with $k \in \mathbb{N}$ permanent requests, in case of $\varphi_{\infty}(n)=1, n \in \mathbb{N}$, an infinite-server system.

A system working under the SDPS discipline and where the requests arrive according to a Poisson process of intensity $\lambda$, the required service times are i.i.d. with df. $B(x):=P(S \leq x)$, where $S$ denotes a generic service time, and finite mean $m_{S}:=E S$ and independent of the arrival process is denoted by $M / G I / S D P S$, the corresponding $r$-server PS system is denoted by $M / G I / r-P S$.

Networks with nodes working under the SDPS discipline are investigated in [Coh], [BP], [CVB], [Zac], [BB1], [BB2]. In particular, for the $M / G I / S D P S$ system some basic results are known, cf. [Coh], which we will use and therefore shortly review in the following. Let $N(t)$ be the number of requests in the system at time $t, Y^{*}(t):=\left(Y_{1}^{*}(t), \ldots, Y_{N(t)}^{*}(t)\right)$ the vector of the residual service times of the $N(t)$ requests in the system at time $t$, ordered randomly, and $\tilde{Y}^{*}(t):=\left(\tilde{Y}_{1}^{*}(t), \ldots, \tilde{Y}_{N(t)}^{*}(t)\right)$ the vector of the attained service times of the $N(t)$ requests in the system at time $t$, ordered randomly. The vector processes $\left(N(t) ; Y^{*}(t)\right), t \in \mathbb{R}$, and $\left(N(t) ; \tilde{Y}^{*}(t)\right)$, $t \in \mathbb{R}$, are Markov processes. The $M / G I / S D P S$ system is stable, i.e., there exist unique stationary processes $\left(N(t) ; Y^{*}(t)\right), t \in \mathbb{R}$, and $\left(N(t) ; \tilde{Y}^{*}(t)\right)$,
$t \in \mathbb{R}$, if and only if

$$
\begin{equation*}
\sum_{n=0}^{\infty} \prod_{\ell=1}^{n} \frac{\varrho}{\ell \varphi(\ell)}<\infty \tag{1.1}
\end{equation*}
$$

where $\varrho:=\lambda m_{S}$ denotes the offered load, cf. [Coh] (7.18). We assume in the following that the system is stable and in steady state, i.e. that (1.1) is fulfilled and that $\left(N(t) ; Y^{*}(t)\right), t \in \mathbb{R}$, and $\left(N(t) ; \tilde{Y}^{*}(t)\right), t \in \mathbb{R}$, are stationary Markov processes. Then the stationary occupancy distribution $p(n):=P(N(t)=n), n \in \mathbb{Z}_{+}$, as well as the stationary distributions of $\left(N(t) ; Y^{*}(t)\right)$ and $\left(N(t) ; \tilde{Y}^{*}(t)\right)$ on $\{N(t)=n\}$ are given by

$$
\begin{align*}
& p(n)=\left(\sum_{m=0}^{\infty} \prod_{\ell=1}^{m} \frac{\varrho}{\ell \varphi(\ell)}\right)^{-1} \prod_{\ell=1}^{n} \frac{\varrho}{\ell \varphi(\ell)}  \tag{1.2}\\
& P\left(N(t)=n ; Y_{1}^{*}(t) \leq y_{1}, \ldots, Y_{n}^{*}(t) \leq y_{n}\right)=p(n) \prod_{\ell=1}^{n} B_{R}\left(y_{\ell}\right) \\
& \quad=P\left(N(t)=n ; \tilde{Y}_{1}^{*}(t) \leq y_{1}, \ldots, \tilde{Y}_{n}^{*}(t) \leq y_{n}\right) \tag{1.3}
\end{align*}
$$

where

$$
\begin{equation*}
B_{R}(x):=\frac{1}{m_{S}} \int_{0}^{x}(1-B(\xi)) \mathrm{d} \xi, \quad x \in \mathbb{R}_{+} \tag{1.4}
\end{equation*}
$$

denotes the stationary residual service time distribution having the density $b_{R}(x)=(1-B(x)) / m_{S}, x \in \mathbb{R}_{+}$, cf. [Coh] (7.19) for the case of phase-type distributed service times, [Zac] for the general case. For the sojourn time $V$ of an arbitrary arriving request with required service time $S$, from Little's law and (1.2) we find

$$
\begin{equation*}
E V=\frac{1}{\lambda} \sum_{n=0}^{\infty} n p(n)=m_{S} \sum_{n=0}^{\infty} \frac{1}{\varphi(n+1)} p(n) \tag{1.5}
\end{equation*}
$$

For the conditional sojourn time $V(\tau)$ of a request with required service time $\tau \in \mathbb{R}_{+}$it holds

$$
\begin{equation*}
E V(\tau)=\frac{\tau}{m_{S}} E V \tag{1.6}
\end{equation*}
$$

cf. [Coh] (7.27). More generally, for $\tau \in \mathbb{R}_{+}, k \in \mathbb{N}$ we have the estimate

$$
\begin{equation*}
\tau^{k}\left(\sum_{n=0}^{\infty} \frac{1}{\varphi(n+1)} p(n)\right)^{k} \leq E\left[V^{k}(\tau)\right] \leq \tau^{k} \sum_{n=0}^{\infty}\left(\frac{1}{\varphi(n+1)}\right)^{k} p(n) \tag{1.7}
\end{equation*}
$$

cf. [BB2] Theorem 3.1. It seems that in case of the general $M / G I / S D P S$ system for $V(\tau)$ and $V$ besides (1.5)-(1.7) there are known only asymptotic results for heavy tailed service times, cf. [GRZ]. However, for special cases several results and numerical algorithms are well known. We mention only a few references. For the $M / G I / 1-P S$ system and special cases, cf. e.g. $[\mathrm{CMT}],[\mathrm{KY}],[\mathrm{Ya} 1],[\mathrm{Ya} 2],[\mathrm{YY} 1],[\mathrm{ZK}]$. The variance of $V(\tau)$ in the $M / M / 2-P S$ system is given in [Tol]. The Laplace-Stieltjes transform (LST) and moments of $V(\tau)$ in the general $M / M / r-P S$ system are treated in [Bra] and in the $M / M / S D P S$ system in [BB1].

The aim of this paper is to derive analytical results and representations for sojourn times in the $M / G I / S D P S$ system. The paper is organized as follows. In Section 2 we analyze a linear system of partial differential equations (PDEs), which has two different stochastic interpretations, implying time reversibility including sojourn times of the $M / G I / S D P S$ system. Moreover, its minimal non negative solution gives the LST of $V(\tau)$, which implies that $V(\tau)$ depends on $B(x)$ for $x>\tau$ only via $m_{S}$ in distribution. In Section 3 we assume that the service time distribution coincides with an exponential distribution in some interval $[0, d)$. We derive a linear system of ordinary differential equations (ODEs) with constant coefficients, whose minimal non negative solution gives the LST of $V(\tau), \tau \in[0, d)$, and which provides corresponding linear systems of ODEs for the moments of $V(\tau), \tau \in[0, d)$. For the case that the service time is the minimum of an exponential and deterministic time we give the LST and the moments of $V$ in terms of minimal non negative solutions of linear systems of ODEs. Numerical results are presented for the variance of $V$ in $M / D / r-P S$. In Section 4 we assume again that the service time distribution coincides with an exponential distribution in some interval $[0, d)$, but we consider the special case of an $M / G I / r-P S$ system. For the $M / G I / 2-P S$ system a representation for the LST of $V(\tau)$, $\tau \in[0, d]$, in terms of the solution of a convolution equation is given. For the limiting case of bounded from below service times, surprisingly simple expressions for the LST and variance of $V(\tau), \tau \in[0, d]$, are derived, which yield in particular the LST and variance of $V(\tau)$ and $V$ in $M / D / 2-P S$.

## 2 Sojourn times in $M / G I / S D P S$

We assume in the following that the system is stable, i.e., that (1.1) is fulfilled, and in steady state. In particular $m_{S}$ is finite. Moreover, for technical reasons - if not stated otherwise - we make in the following the assumption:
(A1) $B(x)$ has a continuous density $b(x)$ and $B(x)<1$ for $x \in \mathbb{R}_{+}$.
For notational convenience let $\bar{B}(x):=1-B(x), \bar{B}_{R}(x):=1-B_{R}(x)$, cf. (1.4), and $\beta(x):=b(x) / \bar{B}(x), \beta_{R}(x):=b_{R}(x) / \bar{B}_{R}(x)$ be the complementary distributions and hazard rates of the service time df. and the stationary residual service time df., respectively. Further we will use several vector notations in this section. If not stated otherwise, let $y:=\left(y_{1}, \ldots, y_{\ell}\right) \in \mathbb{R}_{+}^{\ell}$ where $\ell=m$ or $\ell=n$, respectively, and

$$
\Omega_{\ell}:=\left\{y \in \mathbb{R}_{+}^{\ell}: 0<y_{1}<\ldots<y_{\ell}\right\} .
$$

For $y, \tilde{y} \in \mathbb{R}^{\ell}$ let $y \leq \tilde{y}$ if and only if $y_{i} \leq \tilde{y}_{i}$ for $i=1, \ldots, \ell$.
Besides the randomly ordered residual service times $Y_{1}^{*}(t), \ldots, Y_{N(t)}^{*}(t)$ and attained service times $\tilde{Y}_{1}^{*}(t), \ldots, \tilde{Y}_{N(t)}^{*}(t)$ we need them ordered increasingly. Let $0 \leq Y_{1}(t) \leq \ldots \leq Y_{N(t)}(t)$ be the residual service times of the $N(t)$ requests at time $t$, ordered increasingly, and let $Y(t):=\left(Y_{1}(t), \ldots, Y_{N(t)}(t)\right)$ be the corresponding vector. In view of the SDPS discipline, this implies that the requests are ordered according to their departure instants in this case. Let $0 \leq \tilde{Y}_{1}(t) \leq \ldots \leq \tilde{Y}_{N(t)}(t)$ be the attained service times of the $N(t)$ requests at time $t$, ordered increasingly, and let $\tilde{Y}(t):=\left(\tilde{Y}_{1}(t), \ldots, \tilde{Y}_{N(t)}(t)\right)$ be the corresponding vector. In view of the SDPS discipline, this implies that the requests are ordered reversely to their arrival instants in this case. For $n \in \mathbb{N}, y \in \Omega_{n}$ let

$$
p(n ; y):=\frac{\partial^{n}}{\partial y_{1} \ldots \partial y_{n}} P(N(t)=n ; Y(t) \leq y)
$$

be the density of $Y(t)$ on $\{N(t)=n\}$ and

$$
\tilde{p}(n ; y):=\frac{\partial^{n}}{\partial y_{1} \ldots \partial y_{n}} P(N(t)=n ; \tilde{Y}(t) \leq y)
$$

be the density of $\tilde{Y}(t)$ on $\{N(t)=n\}$. On the boundary of $\Omega_{n}$ let $p(n ; y)$ and $\tilde{p}(n ; y)$ be defined by continuous continuation. The support of $p(n ; y)$ and $\tilde{p}(n ; y)$ is the closure $\bar{\Omega}_{n}$ of $\Omega_{n}$.

Denoting by $\mathcal{S}_{n}$ the set of all permutations of the set $\{1, \ldots, n\}$, from (1.3), (1.4) for $n \in \mathbb{N}, y \in \Omega_{n}$ we obtain

$$
\begin{align*}
& p(n ; y)=\sum_{\pi \in \mathcal{S}_{n}} \frac{\partial^{n}}{\partial y_{1} \ldots \partial y_{n}} P\left(N(t)=n ; Y_{1}^{*}(t) \leq y_{\pi(1)}, \ldots, Y_{n}^{*}(t) \leq y_{\pi(n)}\right) \\
& \quad=n!p(n) \prod_{\ell=1}^{n} b_{R}\left(y_{\ell}\right) \tag{2.1}
\end{align*}
$$

and analogously it follows

$$
\begin{equation*}
\tilde{p}(n ; y)=n!p(n) \prod_{\ell=1}^{n} b_{R}\left(y_{\ell}\right) \tag{2.2}
\end{equation*}
$$

By continuous continuation, (2.1) and (2.2) hold for $n \in \mathbb{N}, y \in \bar{\Omega}_{n}$, too.

### 2.1 PDEs for sojourn times

For the $M / G I / S D P S$ system let the stability condition (1.1) and (A1) be satisfied. Let $V_{\ell}(t), \ell=1, \ldots, N(t)$, be the sojourn time of the request with residual service time $Y_{\ell}(t)$ from time $t$ on until its departure from the system, i.e., its prospective sojourn time from time $t$ on. Since the $Y_{\ell}(t)$ are ordered increasingly, the SDPS discipline implies that the $V_{\ell}(t)$ are ordered increasingly, too, i.e., $0 \leq V_{1}(t) \leq \ldots \leq V_{N(t)}(t)$. Further, $V_{1}(t)=0$ if and only if $Y_{1}(t)=0$. In view of (A1) and the distributional and independence assumptions, for $0<m \leq n, y \in \Omega_{n}$, the LSTs

$$
\begin{equation*}
v_{n, m}(s ; y):=\frac{\partial^{n}}{\partial y_{1} \ldots \partial y_{n}} E\left[e^{-s V_{m}(t)} \mathbb{I}\{N(t)=n, Y(t) \leq y\}\right] \tag{2.3}
\end{equation*}
$$

of $V_{m}(t)$ on $\left\{N(t)=n, Y_{1}(t) \in \mathrm{d} y_{1}, \ldots, Y_{n}(t) \in \mathrm{d} y_{n}\right\}$ are well defined for $s \in \mathbb{R}_{+}$. For fixed $s$ and $0<m \leq n$, let $v_{n, m}(s ; y)$ be defined on the boundary of $\Omega_{n}$ by continuous continuation. Taking into account that in [BB2] the residual service times $Y_{\ell}(t)$ are denoted by $R_{\ell}(t)$, from [BB2] (2.2)-(2.6), (1.2), and (1.4) it follows that the $v_{n, m}(s ; y)$ satisfy the following linear system of PDEs

$$
\begin{align*}
& \varphi(n)\left.\frac{\partial}{\partial \xi} v_{n, m}\left(s ; y_{1}+\xi, \ldots, y_{n}+\xi\right)\right|_{\xi=0} \\
&=-\left(\lambda+s+\varphi(n) \sum_{\ell=1}^{n} \beta\left(y_{\ell}\right)\right) v_{n, m}\left(s ; y_{1}, \ldots, y_{n}\right) \\
&+\varphi(n+1) \sum_{\ell=1}^{n+1} \int_{y_{\ell-1}}^{y_{\ell}} v_{n+1, m+\mathbb{I}\{\ell \leq m\}}\left(s ; y_{1}, \ldots, y_{\ell-1}, \tau, y_{\ell}, \ldots, y_{n}\right) \\
& \beta(\tau) \mathrm{d} \tau \tag{2.4}
\end{align*}
$$

for $0<m \leq n, y \in \Omega_{n}$, where $y_{0}:=0$ and $y_{n+1}:=\infty$, with initial condition

$$
\begin{equation*}
v_{n, 1}\left(s ; 0, y_{2}, \ldots, y_{n}\right)=n!p(n) m_{S}^{-1} \prod_{\ell=2}^{n} b_{R}\left(y_{\ell}\right) \tag{2.5}
\end{equation*}
$$

$$
\begin{equation*}
v_{n, m}\left(s ; 0, y_{2}, \ldots, y_{n}\right)=\frac{\lambda}{\varphi(n)} v_{n-1, m-1}\left(s ; y_{2}, \ldots, y_{n}\right), \quad 1<m \leq n \tag{2.6}
\end{equation*}
$$

for $0 \leq y_{2} \leq \ldots \leq y_{n}$, and that it holds

$$
\begin{equation*}
v_{n, m}(0 ; y)=n!p(n) \prod_{\ell=1}^{n} b_{R}\left(y_{\ell}\right), \quad 0<m \leq n, y \in \bar{\Omega}_{n} \tag{2.7}
\end{equation*}
$$

Note that these equations are consequences of the Kolmogorov forward equations (Fokker-Planck equations) and of (2.1).

Let $\tilde{V}_{\ell}(t), \ell=1, \ldots, N(t)$, be the sojourn time of the request with attained service time $\tilde{Y}_{\ell}(t)$ from its arrival at the system until time $t$. Since the $\tilde{Y}_{\ell}(t)$ are ordered increasingly, the SDPS discipline implies that the $\tilde{V}_{\ell}(t)$ are ordered increasingly, too, i.e. $0 \leq \tilde{V}_{1}(t) \leq \ldots \leq \tilde{V}_{N(t)}(t)$. Further, $\tilde{V}_{1}(t)=0$ if and only if $\tilde{Y}_{1}(t)=0$. In view of (A1) and the distributional and independence assumptions, for $0<m \leq n, y \in \Omega_{n}$, the LSTs

$$
\begin{equation*}
\tilde{v}_{n, m}(s ; y):=\frac{\partial^{n}}{\partial y_{1} \ldots \partial y_{n}} E\left[e^{-s \tilde{V}_{m}(t)} \mathbb{I}\{N(t)=n, \tilde{Y}(t) \leq y\}\right] \tag{2.8}
\end{equation*}
$$

of $\tilde{V}_{m}(t)$ on $\left\{N(t)=n, \tilde{Y}_{1}(t) \in \mathrm{d} y_{1}, \ldots, \tilde{Y}_{n}(t) \in \mathrm{d} y_{n}\right\}$ are well defined for $s \in \mathbb{R}_{+}$. For fixed $s$ and $0<m \leq n$, let $\tilde{v}_{n, m}(s ; y)$ be defined on the boundary of $\Omega_{n}$ by continuous continuation. As $\tilde{v}_{n, m}(0 ; y)$ corresponds to the density of $\tilde{Y}(t)$ on $\{N(t)=n\}$, from (2.2) we find that

$$
\begin{equation*}
\tilde{v}_{n, m}(0 ; y)=\tilde{p}(n ; y)=n!p(n) \prod_{\ell=1}^{n} b_{R}\left(y_{\ell}\right), \quad 0<m \leq n, y \in \bar{\Omega}_{n} \tag{2.9}
\end{equation*}
$$

In the following let $s \in \mathbb{R}_{+}$be fixed. The dynamics of the $M / G I / S D P S$ system during an interval $[t-h, t]$ of length $h$ provide for $0<m \leq n, y \in \Omega_{n}$ the balance condition

$$
\begin{array}{r}
\tilde{v}_{n, m}\left(s ; y_{1}, \ldots, y_{n}\right)=\left(1-\lambda h-\varphi(n) h \sum_{\ell=1}^{n} \beta\left(y_{\ell}\right)\right) e^{-s h} \\
\tilde{v}_{n, m}\left(s ; y_{1}-\varphi(n) h, \ldots, y_{n}-\varphi(n) h\right) \\
+\varphi(n+1) h \sum_{\ell=1}^{n+1} \int_{y_{\ell-1}}^{y_{\ell}} \tilde{v}_{n+1, m+\mathbb{I}\{\ell \leq m\}}\left(s ; y_{1}, \ldots, y_{\ell-1}, \tau, y_{\ell}, \ldots, y_{n}\right) \\
\beta(\tau) \mathrm{d} \tau+o(h) .
\end{array}
$$

The first summand on the r.h.s. corresponds to the situation that during $[t-h, t]$ there is no arrival and no departure; the sojourn time increases
by $h$. The second summand corresponds to departures from the system. Subtracting on both sides $\tilde{v}_{n, m}\left(s ; y_{1}-\varphi(n) h, \ldots, y_{n}-\varphi(n) h\right)$, dividing by $h$ and taking $h \downarrow 0$ provides the following linear system of PDEs

$$
\begin{align*}
&\left.\varphi(n) \frac{\partial}{\partial \xi} \tilde{v}_{n, m}\left(s ; y_{1}+\xi, \ldots, y_{n}+\xi\right)\right|_{\xi=0} \\
&=-\left(\lambda+s+\varphi(n) \sum_{\ell=1}^{n} \beta\left(y_{\ell}\right)\right) \tilde{v}_{n, m}\left(s ; y_{1}, \ldots, y_{n}\right) \\
&+\varphi(n+1) \sum_{\ell=1}^{n+1} \int_{y_{\ell-1}}^{y_{\ell}} \tilde{v}_{n+1, m+\mathbb{I}\{\ell \leq m\}}\left(s ; y_{1}, \ldots, y_{\ell-1}, \tau, y_{\ell}, \ldots, y_{n}\right) \\
& \beta(\tau) \mathrm{d} \tau \tag{2.10}
\end{align*}
$$

for $0<m \leq n, y \in \Omega_{n}$, which correspond to the Kolmogorov forward equations. Taking into consideration arrivals, we find the initial conditions for $0 \leq y_{2} \leq \ldots \leq y_{n}$. As $\tilde{Y}_{1}(t)=0$ implies $\tilde{V}_{1}(t)=0$, from (2.9) and (1.4) we obtain

$$
\begin{equation*}
\tilde{v}_{n, 1}\left(s ; 0, y_{2}, \ldots, y_{n}\right)=\tilde{v}_{n, 1}\left(0 ; 0, y_{2}, \ldots, y_{n}\right)=n!p(n) m_{S}^{-1} \prod_{\ell=2}^{n} b_{R}\left(y_{\ell}\right) . \tag{2.11}
\end{equation*}
$$

In case of $1<m \leq n$ the dynamics provide

$$
\begin{equation*}
\tilde{v}_{n, m}\left(s ; 0, y_{2}, \ldots, y_{n}\right)=\frac{\lambda}{\varphi(n)} \tilde{v}_{n-1, m-1}\left(s ; y_{2}, \ldots, y_{n}\right), \quad 1<m \leq n \tag{2.12}
\end{equation*}
$$

as the arrival probability for an interval of length $h / \varphi(n)$ is $1-e^{-h \lambda / \varphi(n)}$.
Note that the $v_{n, m}(s ; y)$ and the $\tilde{v}_{n, m}(s ; y)$ satisfy the same system of PDEs (2.4)-(2.7).

Lemma 2.1 For any fixed $s \in(0, \infty)$, the linear system of PDEs (2.4) with the initial conditions (2.5), (2.6) and growth condition

$$
\begin{equation*}
0 \leq v_{n, m}(s ; y) \leq v_{n, m}(0 ; y), \quad 0<m \leq n, y \in \bar{\Omega}_{n}, \tag{2.13}
\end{equation*}
$$

where $v_{n, m}(0 ; y)$ is given by (2.7), has at most one solution.
Proof Let $s \in(0, \infty)$ be fixed. Replacing in (2.4) $y_{i}$ by $y_{i}+\eta, i=1, \ldots, n$, integrating with the weight $\exp ((\lambda+s) \eta / \varphi(n)) \prod_{\ell=1}^{n} \bar{B}\left(y_{\ell}\right) / \bar{B}\left(y_{\ell}+\eta\right)$ over $\left[-y_{1}, 0\right]$ with respect to $\eta$ and applying (2.5), (2.6) provides that the system
of PDEs (2.4) with the initial conditions (2.5), (2.6) is equivalent to the following linear system of integral equations for $0<m \leq n, y \in \bar{\Omega}_{n}$ :

$$
\begin{align*}
& v_{n, m}\left(s ; y_{1}, \ldots, y_{n}\right)=\mathbb{I}\{m=1\} n!p(n) m_{S}^{-n} e^{-\frac{\lambda+s}{\varphi(n)} y_{1}}\left(\prod_{\ell=1}^{n} \bar{B}\left(y_{\ell}\right)\right) \\
& +\mathbb{I}\{m>1\} \frac{\lambda}{\varphi(n)} e^{-\frac{\lambda+s}{\varphi(n)} y_{1}}\left(\prod_{\ell=1}^{n} \frac{\bar{B}\left(y_{\ell}\right)}{\bar{B}\left(y_{\ell}-y_{1}\right)}\right) \\
& v_{n-1, m-1}\left(s ; y_{2}-y_{1}, \ldots, y_{n}-y_{1}\right) \\
& +\frac{\varphi(n+1)}{\varphi(n)} \int_{-y_{1}}^{0} e^{\frac{\lambda+s}{\varphi(n)} \xi}\left(\prod_{\ell=1}^{n} \frac{\bar{B}\left(y_{\ell}\right)}{\bar{B}\left(y_{\ell}+\xi\right)}\right) \sum_{\ell=1}^{n+1} \int_{y_{\ell-1}-\mathbb{I}\{\ell=1\} \xi}^{y_{\ell}} \\
& v_{n+1, m+\mathbb{I}\{\ell \leq m\}}\left(s ; y_{1}+\xi, \ldots, y_{\ell-1}+\xi, \tau+\xi, y_{\ell}+\xi, \ldots, y_{n}+\xi\right) \\
& \beta(\tau+\xi) \mathrm{d} \tau \mathrm{~d} \xi . \tag{2.14}
\end{align*}
$$

Assume that the system of integral equations (2.14) has two different solutions, where both solutions fulfill the growth condition (2.13). Then the difference $\bar{v}_{n, m}(s ; y)$ of these solutions satisfies the homogenized version of (2.14). For $0<m \leq n$ let $\kappa_{n, m} \in \mathbb{R}_{+}$denote the smallest number such that $\left|\bar{v}_{n, m}(s ; y)\right| \leq \kappa_{n, m} v_{n, m}(0 ; y), y \in \bar{\Omega}_{n}$. Note that $\kappa_{n, m} \in(0,1]$ due to the growth condition. Let $\kappa_{n-1,0}:=0$ for notational convenience and let $\kappa_{0}:=\sup _{0<m \leq n} \kappa_{n, m}$. The triangle inequality applied to the homogenized version of $(2.14)$, the definitions of $\kappa_{n, m}$ and $\kappa_{0}$, and (2.7), (1.4), (1.2) provide after some algebra for $0<m \leq n, y \in \bar{\Omega}_{n}$ that

$$
\left.\begin{array}{l}
\left|\bar{v}_{n, m}\left(s ; y_{1}, \ldots, y_{n}\right)\right| \leq \kappa_{n-1, m-1} \frac{\lambda}{\varphi(n)} e^{-\frac{\lambda+s}{\varphi(n)} y_{1}}\left(\prod_{\ell=1}^{n} \frac{\bar{B}\left(y_{\ell}\right)}{\bar{B}\left(y_{\ell}-y_{1}\right)}\right) \\
v_{n-1, m-1}\left(0 ; y_{2}-y_{1}, \ldots, y_{n}-y_{1}\right) \\
+ \\
\kappa_{0} \frac{\varphi(n+1)}{\varphi(n)} \int_{-y_{1}}^{0} e^{\frac{\lambda+s}{\varphi(n)} \xi}\left(\prod_{\ell=1}^{n} \frac{\bar{B}\left(y_{\ell}\right)}{\bar{B}\left(y_{\ell}+\xi\right)}\right) \sum_{\ell=1}^{n+1} \int_{y_{\ell-1}-\mathbb{I}\{\ell=1\} \xi}^{y_{\ell}} \\
v_{n+1, m+\mathbb{I}\{\ell \leq m\}}\left(0 ; y_{1}+\xi, \ldots, y_{\ell-1}+\xi, \tau+\xi, y_{\ell}+\xi, \ldots, y_{n}+\xi\right) \\
\beta(\tau+\xi) \mathrm{d} \tau \mathrm{~d} \xi
\end{array}\right] \begin{aligned}
& \quad\left(\kappa_{n-1, m-1} e^{-\frac{\lambda+s}{\varphi(n)} y_{1}}+\frac{\lambda}{\lambda+s} \kappa_{0}\left(1-e^{-\frac{\lambda+s}{\varphi(n)} y_{1}}\right)\right) v_{n, m}\left(0 ; y_{1}, \ldots, y_{n}\right) \\
& \leq \max \left(\kappa_{n-1, m-1}, \frac{\lambda}{\lambda+s} \kappa_{0}\right) v_{n, m}\left(0 ; y_{1}, \ldots, y_{n}\right)
\end{aligned}
$$

Therefore, by definition it holds

$$
\begin{equation*}
\kappa_{n, m} \leq \max \left(\kappa_{n-1, m-1}, \frac{\lambda}{\lambda+s} \kappa_{0}\right), \quad 0<m \leq n \tag{2.15}
\end{equation*}
$$

Let $j \in \mathbb{Z}_{+}$be arbitrarily fixed. In view of $\kappa_{j, 0}=0$, from (2.15) we find $\kappa_{j+1,1} \leq \frac{\lambda}{\lambda+s} \kappa_{0}$. Now induction on $m \in \mathbb{N}$ yields $\kappa_{j+m, m} \leq \frac{\lambda}{\lambda+s} \kappa_{0}$ in view of (2.15). Thus we obtain $\kappa_{0} \leq \frac{\lambda}{\lambda+s} \kappa_{0}$, which implies the contradiction $\kappa_{0} \leq 0$.

From Lemma 2.1 we conclude that the Kolmogorov forward equations (2.4)-(2.7) and (2.9)-(2.12) provide a complete description of the LSTs $v_{n, m}(s ; y)$ and $\tilde{v}_{n, m}(s ; y)$, respectively. Moreover, since the $v_{n, m}(s ; y)$ and the $\tilde{v}_{n, m}(s ; y)$ satisfy the same system of PDEs $(2.4)-(2.7)$, and taking into account (2.1), (2.2), from Lemma 2.1 we obtain the following time reversibility result for $M / G I / S D P S$ systems:

Theorem 2.1 Let the stability condition (1.1) for the $M / G I / S D P S$ system with (A1) be satisfied. Then it holds

$$
\begin{equation*}
\tilde{v}_{n, m}(s ; y)=v_{n, m}(s ; y), \quad 0<m \leq n, y \in \bar{\Omega}_{n}, s \in \mathbb{R}_{+} \tag{2.16}
\end{equation*}
$$

$$
\begin{array}{r}
P\left(\tilde{V}_{m}(t) \leq x \mid N(t)=n, \tilde{Y}(t)=y\right)=P\left(V_{m}(t) \leq x \mid N(t)=n, Y(t)=y\right) \\
0<m \leq n, y \in \bar{\Omega}_{n}, x \in \mathbb{R}_{+} \tag{2.17}
\end{array}
$$

Because of the $S D P S$ discipline, from a probabilistic point of view, for $0<m \leq n, y \in \bar{\Omega}_{n}$ the sojourn time $V_{m}(t)$ conditioned that $N(t)=n$, $Y(t)=y$ depends only on $y_{1}, \ldots, y_{m}$ and the total number $n$ of requests in the system since the requests with residual service times $y_{m+1}, \ldots, y_{n}$ have residual service times of an amount greater or equal to $y_{m}$ and are thus in the system at least as long as the request with service time $y_{m}$. However, in the following a rigorous proof will be given. In view of (2.16) and (2.7), (2.9), we try the substitution

$$
\begin{array}{r}
\tilde{v}_{n, m}\left(s ; y_{1}, \ldots, y_{n}\right)=v_{n, m}\left(s ; y_{1}, \ldots, y_{n}\right) \\
=u_{n, m}\left(s ; y_{1}, \ldots, y_{m}\right) \prod_{\ell=m+1}^{n} b_{R}\left(y_{\ell}\right), \tag{2.18}
\end{array}
$$

where the $u_{n, m}(s ; y), 0<m \leq n, y \in \bar{\Omega}_{m}$, let be continuous functions. The system of PDEs $(2.4)$ is fulfilled if the $u_{n, m}(s ; y)$ satisfy the following system
of PDEs for $0<m \leq n, y \in \Omega_{m}$ :

$$
\begin{align*}
&\left.\varphi(n) \frac{\partial}{\partial \xi} u_{n, m}\left(s ; y_{1}+\xi, \ldots, y_{m}+\xi\right)\right|_{\xi=0} \\
&=-\left(\lambda+s+\varphi(n) \sum_{\ell=1}^{m} \beta\left(y_{\ell}\right)\right) u_{n, m}\left(s ; y_{1}, \ldots, y_{m}\right) \\
&+\varphi(n+1) \sum_{\ell=1}^{m} \int_{y_{\ell-1}}^{y_{\ell}} u_{n+1, m+1}\left(s ; y_{1}, \ldots, y_{\ell-1}, \tau, y_{\ell}, \ldots, y_{m}\right) \\
&+\varphi(\tau+1) b_{R}\left(y_{m}\right) u_{n+1, m}\left(s ; y_{1}, \ldots, y_{m}\right) . \tag{2.19}
\end{align*}
$$

The initial condition (2.5) is fulfilled if for $1=m \leq n$

$$
\begin{equation*}
u_{n, 1}(s ; 0)=n!p(n) m_{S}^{-1} \tag{2.20}
\end{equation*}
$$

and the initial condition (2.6) is fulfilled if for $1<m \leq n, 0 \leq y_{2} \leq \ldots \leq y_{m}$

$$
\begin{equation*}
u_{n, m}\left(s ; 0, y_{2}, \ldots, y_{m}\right)=\frac{\lambda}{\varphi(n)} u_{n-1, m-1}\left(s ; y_{2}, \ldots, y_{m}\right) \tag{2.21}
\end{equation*}
$$

Note that (2.7) is fulfilled if for $0<m \leq n, y \in \bar{\Omega}_{m}$

$$
\begin{equation*}
u_{n, m}\left(0 ; y_{1}, \ldots, y_{m}\right)=n!p(n) \prod_{\ell=1}^{m} b_{R}\left(y_{\ell}\right) \tag{2.22}
\end{equation*}
$$

Lemma 2.2 For any $s \in \mathbb{R}_{+}$, the linear system of PDEs (2.19) with the initial conditions (2.20), (2.21) has a minimal non negative solution, and the minimal non negative solution is bounded by $u_{n, m}(0 ; y)$, i.e. by the r.h.s. of (2.22).

Proof Analogously to the derivation of (2.14) we find that the system of PDEs (2.19) with initial conditions (2.20), (2.21) is equivalent to the following system of integral equations for $0<m \leq n, y \in \bar{\Omega}_{m}$ :

$$
\begin{aligned}
& u_{n, m}\left(s ; y_{1}, \ldots, y_{m}\right)=e^{-\frac{\lambda+s}{\varphi(n)} y_{1}}\left(\prod_{\ell=1}^{m} \frac{\bar{B}\left(y_{\ell}\right)}{\bar{B}\left(y_{\ell}-y_{1}\right)}\right)\left(\mathbb{I}\{m=1\} n!p(n) m_{S}^{-1}\right. \\
& \\
& \left.+\mathbb{I}\{m>1\} \frac{\lambda}{\varphi(n)} u_{n-1, m-1}\left(s ; y_{2}-y_{1}, \ldots, y_{m}-y_{1}\right)\right) \\
& \quad+\frac{\varphi(n+1)}{\varphi(n)} \int_{-y_{1}}^{0} e^{\frac{\lambda+s}{\varphi(n)} \xi}\left(\prod_{\ell=1}^{m} \frac{\bar{B}\left(y_{\ell}\right)}{\bar{B}\left(y_{\ell}+\xi\right)}\right)
\end{aligned}
$$

$$
\begin{align*}
& \left(\sum _ { \ell = 1 } ^ { m } \int _ { y _ { \ell - 1 } - \mathbb { I } \{ \ell = 1 \} \xi } ^ { y \ell } u _ { n + 1 , m + 1 } \left(s ; y_{1}+\xi, \ldots, y_{\ell-1}+\xi, \tau+\xi\right.\right. \\
& \left.\quad y_{\ell}+\xi, \ldots, y_{m}+\xi\right) \beta(\tau+\xi) \mathrm{d} \tau \\
& \left.\quad+b_{R}\left(y_{m}+\xi\right) u_{n+1, m}\left(s ; y_{1}+\xi, \ldots, y_{m}+\xi\right)\right) \mathrm{d} \xi \tag{2.23}
\end{align*}
$$

This system of integral equations can be solved by the method of successive approximation starting from $u_{n, m ; 0}\left(s ; y_{1}, \ldots, y_{m}\right) \equiv 0$ and defining $u_{n, m ; i+1}\left(s ; y_{1}, \ldots, y_{m}\right)$ recursively with respect to $i$ by the r.h.s. of $(2.23)$, where the $u_{n^{\prime}, m^{\prime}}\left(s ; \tilde{y}_{1}, \ldots, \tilde{y}_{m^{\prime}}\right)$ are replaced by $u_{n^{\prime}, m^{\prime} ; i}\left(s ; \tilde{y}_{1}, \ldots, \tilde{y}_{m^{\prime}}\right)$. For this recursion by induction on $i$ it follows that for fixed $0<m \leq n$, $0 \leq y_{1} \leq \ldots \leq y_{m}$ the $u_{n, m ; i}\left(s ; y_{1}, \ldots, y_{m}\right)$ are monotonically increasing with respect to $i$ and that it holds

$$
\begin{equation*}
u_{n, m ; i}\left(s ; y_{1}, \ldots, y_{m}\right) \leq u_{n, m ; i}\left(0 ; y_{1}, \ldots, y_{m}\right) \tag{2.24}
\end{equation*}
$$

Moreover, if $u_{n, m}\left(s ; y_{1}, \ldots, y_{m}\right)$ is any non negative solution of the system of PDEs (2.19) with initial conditions (2.20), (2.21) for fixed $s \in \mathbb{R}_{+}$, then $u_{n, m}\left(s ; y_{1}, \ldots, y_{m}\right)$ is a non negative solution of (2.23), and thus it follows that $u_{n, m ; i}\left(s ; y_{1}, \ldots, y_{m}\right)-u_{n, m}\left(s ; y_{1}, \ldots, y_{m}\right)$ satisfies the corresponding homogeneous recursion with respect to $i$. Therefore induction on $i$ provides

$$
\begin{equation*}
u_{n, m ; i}\left(s ; y_{1}, \ldots, y_{m}\right) \leq u_{n, m}\left(s ; y_{1}, \ldots, y_{m}\right) \tag{2.25}
\end{equation*}
$$

As, because of (1.2) and (1.4), the r.h.s. of (2.22) is a solution of (2.19) and $(2.20)$, (2.21) for $s=0$, thus $u_{n, m ; i}\left(0 ; y_{1}, \ldots, y_{m}\right)$ is bounded by the r.h.s. of $(2.22)$, and in view of $(2.24), u_{n, m ; i}\left(s ; y_{1}, \ldots, y_{m}\right)$ is bounded by the r.h.s. of $(2.22)$ for any $s \in \mathbb{R}_{+}$. Thus for any $s \in \mathbb{R}_{+}$, the limit $\lim _{i \rightarrow \infty} u_{n, m ; i}\left(s ; y_{1}, \ldots, y_{m}\right)$ exists pointwise and is, due to Lebesgue's theorem, a non negative solution of (2.23). This solution is the minimal non negative solution of (2.23) because of (2.25). Moreover, in view of (2.24), it is bounded by the minimal non negative solution of $(2.23)$ for $s=0$, and thus by the r.h.s. of $(2.22)$ as the r.h.s. of $(2.22)$ is a non negative solution of $(2.19)$ and $(2.20),(2.21)$ for $s=0$, i.e. of $(2.23)$ for $s=0$.

Summarizing Lemma 2.1 and Lemma 2.2 we have proved the following
Theorem 2.2 Let the stability condition (1.1) for the M/GI/SDPS system with (A1) be satisfied.

Then for $s \in(0, \infty)$, the LSTs $v_{n, m}(s ; y)$ and $\tilde{v}_{n, m}(s ; y)$ are given by (2.18) for $0<m \leq n, y \in \bar{\Omega}_{n}$, where $u_{n, m}(s ; y), y \in \bar{\Omega}_{m}$, is the minimal non negative solution of the linear system of PDEs (2.19) with the initial conditions (2.20), (2.21).

### 2.2 LST and moments of $V(\tau)$

For the $M / G I / S D P S$ system let the stability condition (1.1) and (A1) be satisfied. For $s \in \mathbb{R}_{+}, 0<m \leq n, x \in \mathbb{R}_{+}$let

$$
\begin{equation*}
g_{n, m}(s, x):=\frac{\partial}{\partial x} E\left[e^{-s V_{m}(t)} \mathbb{I}\left\{N(t)=n, Y_{m}(t) \leq x\right\}\right] . \tag{2.26}
\end{equation*}
$$

Note that in view of Theorem 2.1 it also holds

$$
g_{n, m}(s, x)=\frac{\partial}{\partial x} E\left[e^{-s \tilde{V}_{m}(t)} \mathbb{I}\left\{N(t)=n, \tilde{Y}_{m}(t) \leq x\right\}\right] .
$$

From Theorem 2.2 by integrating $v_{n, m}(s ; y)$ over

$$
0 \leq y_{1} \leq \ldots \leq y_{m-1} \leq x \leq y_{m+1} \leq \ldots \leq y_{n}
$$

with respect to $\mathrm{d} y_{1} \ldots \mathrm{~d} y_{m-1} \mathrm{~d} y_{m+1} \ldots \mathrm{~d} y_{n}$ we obtain that

$$
\begin{equation*}
g_{n, m}(s, x)=e_{n-m}(x) f_{n, m}(s, x), \tag{2.27}
\end{equation*}
$$

where

$$
\begin{align*}
& e_{\ell}(x):=\frac{\bar{B}_{R}(x)^{\ell}}{\ell!},  \tag{2.28}\\
& f_{n, m}(s, x):=\int_{0 \leq y_{1} \leq \ldots \leq y_{m-1} \leq x} u_{n, m}\left(s ; y_{1}, \ldots, y_{m-1}, x\right) \mathrm{d} y_{1} \ldots \mathrm{~d} y_{m-1} . \tag{2.29}
\end{align*}
$$

For $s \in(0, \infty), 0<m \leq n, x \in \mathbb{R}_{+}, \ell \in \mathbb{Z}_{+}$let

$$
\begin{equation*}
g_{n, m}^{(\ell)}(s, x):=(-1)^{\ell} \frac{\partial^{\ell}}{\partial s^{\ell}} g_{n, m}(s, x) . \tag{2.30}
\end{equation*}
$$

From (2.26) it follows that

$$
\begin{equation*}
g_{n, m}^{(\ell)}(s, x)=\frac{\partial}{\partial x} E\left[V_{m}^{\ell}(t) e^{-s V_{m}(t)} \mathbb{I}\left\{N(t)=n, Y_{m}(t) \leq x\right\}\right], \tag{2.31}
\end{equation*}
$$

which implies

$$
\begin{equation*}
0 \leq g_{n, m}^{(\ell)}(s, x) \leq \ell!s^{-\ell} g_{n, m}(0, x) \tag{2.32}
\end{equation*}
$$

in view of $v^{\ell} e^{-s v} \leq \ell!s^{-\ell}$. Moreover, from (2.31) it follows that $g_{n, m}^{(\ell)}(s, x)$ is monotonically decreasing with respect to $s \in(0, \infty)$. Thus the limit

$$
\begin{equation*}
g_{n, m}^{(\ell)}(x):=\lim _{s \downarrow 0} g_{n, m}^{(\ell)}(s, x), \quad 0<m \leq n, x \in \mathbb{R}_{+}, \ell \in \mathbb{Z}_{+}, \tag{2.33}
\end{equation*}
$$

exists, but it may be infinite for some $\ell \in \mathbb{N}$.
Let $V(n, \tau), n \in \mathbb{Z}_{+}, \tau \in \mathbb{R}_{+}$, be the sojourn time of a tagged arriving request with required service time $\tau$ ( $\tau$-request) finding $n$ requests at its arrival in the system, and let $V(\tau), \tau \in \mathbb{R}_{+}$, be the sojourn time of a tagged arriving $\tau$-request. For the $M / G I / S D P S$ system the following representations for the LSTs and moments of $V(n, \tau)$ and $V(\tau)$ are known, cf. [BB2] Theorem 2.1, Theorem 3.1 and Theorem 3.2:

Theorem 2.3 For the M/GI/SDPS system let the stability condition (1.1) and (A1) be satisfied. Then for $s \in \mathbb{R}_{+}$and $\tau \in \mathbb{R}_{+}$the LSTs of $V(n, \tau)$, $n \in \mathbb{Z}_{+}$, and $V(\tau)$ are given by

$$
\begin{align*}
& E\left[e^{-s V(n, \tau)}\right]=\frac{\varphi(n+1)}{\lambda(\tau) p(n)} \sum_{m=1}^{n+1} g_{n+1, m}(s, \tau)  \tag{2.34}\\
& E\left[e^{-s V(\tau)}\right]=\frac{1}{\lambda(\tau)} \sum_{n=1}^{\infty} \varphi(n) \sum_{m=1}^{n} g_{n, m}(s, \tau) \tag{2.35}
\end{align*}
$$

respectively, where

$$
\begin{equation*}
\lambda(x):=\lambda \bar{B}(x), \quad x \in \mathbb{R}_{+} . \tag{2.36}
\end{equation*}
$$

If additionally

$$
\begin{equation*}
\sum_{n=0}^{\infty}\left(\frac{1}{\varphi(n+1)}\right)^{k} p(n)<\infty \tag{2.37}
\end{equation*}
$$

for some $k \in \mathbb{N}$, then the $k$ th moments of $V(n, \tau), n \in \mathbb{Z}_{+}$, and $V(\tau)$ are finite for $\tau \in \mathbb{R}_{+}$, and it holds

$$
\begin{align*}
& E\left[V^{k}(n, \tau)\right]=\frac{\varphi(n+1)}{\lambda(\tau) p(n)} \sum_{m=1}^{n+1} g_{n+1, m}^{(k)}(\tau),  \tag{2.38}\\
& E\left[V^{k}(\tau)\right]=\frac{1}{\lambda(\tau)} \sum_{n=1}^{\infty} \varphi(n) \sum_{m=1}^{n} g_{n, m}^{(k)}(\tau)=k \int_{0}^{\tau} \sum_{n=1}^{\infty} \sum_{m=1}^{n} \frac{g_{n, m}^{(k-1)}(x)}{\lambda(x)} \mathrm{d} x . \tag{2.39}
\end{align*}
$$

Theorem 2.3 provides the following insensitivity property of $V(\tau)$ in M/GI/SDPS.

Theorem 2.4 Let the stability condition (1.1) for the $M / G I / S D P S$ be satisfied. Then the conditional sojourn times $V(n, \tau), n \in \mathbb{Z}_{+}$, and $V(\tau)$ depend on the service time distribution $B(x)$ for $x>\tau$ only via the mean service time $m_{S}$ in distribution.

Proof Suppose first that (A1) is fulfilled. Then $u_{n, m}\left(s ; y_{1}, \ldots, y_{m}\right)$ is the minimal non negative solution of the linear system of PDEs (2.19) with initial conditions $(2.20),(2.21)$. Therefore $u_{n, m}\left(s ; y_{1}, \ldots, y_{m}\right)$ depends on $B(x)$ for $x>y_{m}$ only via $m_{S}$, and hence $f_{n, m}(s, \tau)$ depends on $B(x)$ for $x>\tau$ only via $m_{S}$ because of (2.29). In view of (2.28), (1.4), (2.27), and (2.36), thus the assertion follows from (2.34) and (2.35). The case of a general distribution $B(x)$ of the service time with finite mean $m_{S}$ is obtained by taking the limit in distribution of a sequence of service time distributions $B_{\nu}(x), \nu=1,2, \ldots$, where the service times have the given mean $m_{S}$ and the $B_{\nu}(x)$ fulfill (A1) and converge weakly to $B(x)$.

## 3 Locally exponential service times

We assume now that the service time $S$ has finite mean $m_{S}$ and that its distribution $B(x)$ coincides with an exponential distribution in a neighborhood of zero, i.e.

$$
\begin{equation*}
B(x)=1-e^{-\mu x}, \quad x \in[0, d) \tag{3.1}
\end{equation*}
$$

where $\mu \in \mathbb{R}_{+}$, for some $d \in(0, \infty)$. Moreover, for technical reasons we assume (A1) again, i.e., we assume that $B(x)$ has a continuous density $b(x)$ and that $B(x)<1$ for $x \in \mathbb{R}_{+}$.

Again we assume in the following that the system is stable, i.e. that (1.1) is fulfilled, and in steady state. In view of (3.1), for $0<m \leq n$, $0<y_{1}<\ldots<y_{m}<d$ the system of PDEs (2.19) simplifies to

$$
\begin{aligned}
\varphi(n) & \left.\frac{\partial}{\partial \xi} u_{n, m}\left(s ; y_{1}+\xi, \ldots, y_{m}+\xi\right)\right|_{\xi=0} \\
= & -(\lambda+s+\varphi(n) m \mu) u_{n, m}\left(s ; y_{1}, \ldots, y_{m}\right) \\
& +\varphi(n+1) \mu \sum_{\ell=1}^{m} \int_{y_{\ell-1}}^{y_{\ell}} u_{n+1, m+1}\left(s ; y_{1}, \ldots, y_{\ell-1}, \tau, y_{\ell}, \ldots, y_{m}\right) \mathrm{d} \tau \\
& +\varphi(n+1) m_{S}^{-1} e^{-\mu y_{m}} u_{n+1, m}\left(s ; y_{1}, \ldots, y_{m}\right)
\end{aligned}
$$

Replacing $y_{i}$ by $y_{i}+\eta, i=1, \ldots, m$, and integrating over $\left[-y_{1}, 0\right]$ with respect to $\eta$ provides the system of integral equations

$$
\begin{aligned}
& u_{n, m}\left(s ; y_{1}, \ldots, y_{m}\right)-u_{n, m}\left(s ; 0, y_{2}-y_{1}, \ldots, y_{m}-y_{1}\right) \\
& =\frac{1}{\varphi(n)} \int_{-y_{1}}^{0}\left(-(\lambda+s+\varphi(n) m \mu) u_{n, m}\left(s ; y_{1}+\xi, \ldots, y_{m}+\xi\right)\right. \\
& \quad+\varphi(n+1) \mu \sum_{\ell=1}^{m} \int_{y_{\ell-1}-\mathbb{I}\{\ell=1\} \xi}^{y_{\ell}} u_{n+1, m+1}\left(s ; y_{1}+\xi, \ldots, y_{\ell-1}+\xi\right. \\
& \left.\quad \tau+\xi, y_{\ell}+\xi, \ldots, y_{m}+\xi\right) \mathrm{d} \tau \\
& \left.\quad+\varphi(n+1) m_{S}^{-1} e^{-\mu\left(y_{m}+\xi\right)} u_{n+1, m}\left(s ; y_{1}+\xi, \ldots, y_{m}+\xi\right)\right) \mathrm{d} \xi
\end{aligned}
$$

In view of (2.29), integrating over $0 \leq y_{1} \leq \ldots \leq y_{m}=x<d$ with respect to $\mathrm{d} y_{1} \ldots \mathrm{~d} y_{m-1}$ and applying Fubini's theorem yields after some algebra

$$
\begin{align*}
& f_{n, m}(s, x)-\int_{0 \leq \xi_{2} \leq \ldots \leq \xi_{m} \leq x} u_{n, m}\left(s ; 0, \xi_{2}, \ldots, \xi_{m}\right) \mathrm{d} \xi_{2} \ldots \mathrm{~d} \xi_{m} \\
& =\frac{1}{\varphi(n)} \int_{0}^{x}\left(-(\lambda+s+\varphi(n) m \mu) f_{n, m}\left(s, \xi_{m}\right)\right. \\
& \\
& +\varphi(n+1) m \mu f_{n+1, m+1}\left(s, \xi_{m}\right)  \tag{3.2}\\
& \\
& \left.+\varphi(n+1) m_{S}^{-1} e^{-\mu \xi_{m}} f_{n+1, m}\left(s, \xi_{m}\right)\right) \mathrm{d} \xi_{m}
\end{align*}
$$

Because of (2.20), (2.21) and (2.29), from (3.2) we obtain the linear system of ODEs

$$
\begin{align*}
\varphi(n) & \frac{\partial}{\partial x} f_{n, m}(s, x)=-(\lambda+s+\varphi(n) m \mu) f_{n, m}(s, x) \\
& +\mathbb{I}\{m>1\} \lambda f_{n-1, m-1}(s, x)+\varphi(n+1) m \mu f_{n+1, m+1}(s, x) \\
& +\varphi(n+1) m_{S}^{-1} e^{-\mu x} f_{n+1, m}(s, x), \quad 0<m \leq n, 0<x<d \tag{3.3}
\end{align*}
$$

with the initial condition

$$
\begin{equation*}
f_{n, m}(s, 0)=\mathbb{I}\{m=1\} n!p(n) m_{S}^{-1}, \quad 0<m \leq n \tag{3.4}
\end{equation*}
$$

Note that from $(2.29),(2.22),(1.4)$, and (3.1) it follows

$$
\begin{equation*}
f_{n, m}(0, x)=n!p(n)\left(m_{S} e^{\mu x}\right)^{-m} \frac{F^{m-1}(x)}{(m-1)!}, \quad 0<m \leq n, 0 \leq x<d \tag{3.5}
\end{equation*}
$$

where

$$
F(x):=\left\{\begin{array}{ll}
\left(e^{\mu x}-1\right) / \mu, & \mu \neq 0,  \tag{3.6}\\
x, & \mu=0,
\end{array} \quad x \in \mathbb{R}_{+}\right.
$$

Let

$$
\begin{equation*}
h_{n, m}(s, x):=\frac{1}{p(0)}\left(m_{S} e^{\mu x}\right)^{m-n} f_{n, m}(s, x), \quad 0<m \leq n, 0 \leq x<d \tag{3.7}
\end{equation*}
$$

In view of (2.27), (2.28), (1.4), (3.1), (3.6), and (3.7), it holds

$$
\begin{equation*}
g_{n, m}(s, x)=d_{n-m}(x) h_{n, m}(s, x), \quad 0<m \leq n, 0 \leq x<d \tag{3.8}
\end{equation*}
$$

where

$$
\begin{equation*}
d_{\ell}(x):=\frac{p(0)}{\ell!}\left(m_{S} e^{\mu x}-F(x)\right)^{\ell}, \quad \ell \in \mathbb{Z}_{+}, x \in \mathbb{R}_{+} \tag{3.9}
\end{equation*}
$$

Note that $d_{\ell}(x)>0$ for $0 \leq x<d$ as

$$
m_{S}=\int_{0}^{\infty} \bar{B}(x) \mathrm{d} x \geq \int_{0}^{d} \bar{B}(x) \mathrm{d} x=e^{-\mu d} F(d)
$$

Because of (3.7), (3.3), (3.4), and (1.2), the $h_{n, m}$ fulfill the linear system of ODEs with constant coefficients

$$
\begin{align*}
\varphi(n) & \frac{\partial}{\partial x} h_{n, m}(s, x)=-(\lambda+s+\varphi(n) n \mu) h_{n, m}(s, x) \\
& +\mathbb{I}\{m>1\} \lambda h_{n-1, m-1}(s, x)+\varphi(n+1) m \mu h_{n+1, m+1}(s, x) \\
& +\varphi(n+1) h_{n+1, m}(s, x), \quad 0<m \leq n, 0<x<d \tag{3.10}
\end{align*}
$$

with initial condition

$$
\begin{equation*}
h_{n, m}(s, 0)=\mathbb{I}\{m=1\} \prod_{j=1}^{n} \frac{\lambda}{\varphi(j)}, \quad 0<m \leq n \tag{3.11}
\end{equation*}
$$

From (3.7), (3.5), and (1.2) it follows

$$
\begin{equation*}
h_{n, m}(0, x)=\left(\prod_{j=1}^{n} \frac{\lambda}{\varphi(j)}\right) e^{-n \mu x} \frac{F^{m-1}(x)}{(m-1)!}, \quad 0<m \leq n, 0 \leq x<d \tag{3.12}
\end{equation*}
$$

Replacing in (3.10) $x$ by $\xi$, integrating appropriately weighted over $[0, x]$ with respect to $\xi$ and applying (3.11) provides that the system of ODEs
(3.10) with initial condition (3.11) is equivalent to the following system of integral equations:

$$
\begin{array}{r}
h_{n, m}(s, x)=h_{n, m}^{*}(s, x)+\frac{1}{\varphi(n)} \int_{0}^{x}\left(\mathbb{I}\{m>1\} \lambda h_{n-1, m-1}(s, \xi)\right. \\
\left.+\varphi(n+1) m \mu h_{n+1, m+1}(s, \xi)+\varphi(n+1) h_{n+1, m}(s, \xi)\right) \\
e^{-\left(\frac{\lambda+s}{\varphi(n)}+n \mu\right)(x-\xi)} \mathrm{d} \xi, \quad 0<m \leq n, 0 \leq x<d \tag{3.13}
\end{array}
$$

where

$$
\begin{equation*}
h_{n, m}^{*}(s, x)=\mathbb{I}\{m=1\}\left(\prod_{j=1}^{n} \frac{\lambda}{\varphi(j)}\right) e^{-\left(\frac{\lambda+s}{\varphi(n)}+n \mu\right) x}, \quad 0<m \leq n, 0 \leq x<d \tag{3.14}
\end{equation*}
$$

Lemma 3.1 Let $h_{n, m}^{*}(s, x)$ be arbitrary continuous functions.
Then for any fixed $s \in(0, \infty)$, the linear system of integral equations (3.13) with growth condition

$$
\begin{equation*}
\left|h_{n, m}(s, x)\right| \leq c h_{n, m}(0, x), \quad 0<m \leq n, 0 \leq x<d \tag{3.15}
\end{equation*}
$$

for some $c>0$, where $h_{n, m}(0, x)$ is given by (3.12), has at most one solution.
Proof The proof runs analogously to the proof of Lemma 2.1. Assume that the system of integral equations (3.13) has two different solutions, where both solutions fulfill the growth condition (3.15). Then the difference $\bar{h}_{n, m}(s, x)$ of these solutions satisfies the homogenized version of (3.13), i.e. (3.13) in case of $h_{n, m}^{*}(s, x)=0$. For $0<m \leq n$ let $\kappa_{n, m} \in \mathbb{R}_{+}$denote the smallest number such that $\left|\bar{h}_{n, m}(s, x)\right| \leq \kappa_{n, m} h_{n, m}(0, x), 0 \leq x<d$. Note that $\kappa_{n, m} \in(0,2 c]$ due to the growth condition. Let $\kappa_{n-1,0}:=0$ for notational convenience and let $\kappa_{0}:=\sup _{0<m \leq n} \kappa_{n, m}$. The triangle inequality applied to (3.13), the definitions of $\kappa_{n, m}$ and $\kappa_{0}$, and (3.12), (3.6) provide after some algebra for $0<m \leq n, 0 \leq x<d$ that

$$
\begin{aligned}
& \left|\bar{h}_{n, m}(s, x)\right| \leq \frac{1}{\varphi(n)} \int_{0}^{x}\left(\kappa_{n-1, m-1} \lambda h_{n-1, m-1}(0, \xi)\right. \\
& \left.\quad+\kappa_{0} \varphi(n+1) m \mu h_{n+1, m+1}(0, \xi)+\kappa_{0} \varphi(n+1) h_{n+1, m}(0, \xi)\right) \\
& \quad e^{-\left(\frac{\lambda+s}{\varphi(n)}+n \mu\right)(x-\xi)} \mathrm{d} \xi \\
& =\left(\prod_{j=1}^{n} \frac{\lambda}{\varphi(j)}\right) \frac{e^{-\left(\frac{\lambda+s}{\varphi(n)}+n \mu\right) x}}{(m-1)!} \int_{0}^{x}\left(\kappa_{n-1, m-1}(m-1) F^{m-2}(\xi) e^{\mu \xi}\right.
\end{aligned}
$$

$$
\begin{aligned}
& \left.\quad+\kappa_{0} \frac{\lambda}{\varphi(n)} F^{m-1}(\xi)\right) e^{\frac{\lambda+s}{\varphi(n)} \xi} \mathrm{d} \xi \\
& \leq \max \left(\kappa_{n-1, m-1}, \frac{\lambda}{\lambda+s} \kappa_{0}\right)\left(\prod_{j=1}^{n} \frac{\lambda}{\varphi(j)}\right) \frac{e^{-\left(\frac{\lambda+s}{\varphi(n)}+n \mu\right) x}}{(m-1)!} \\
& \quad\left(\left.F^{m-1}(\xi) e^{\frac{\lambda+s}{\varphi(n)} \xi}\right|_{\xi=0} ^{x}\right) \\
& \leq \max \left(\kappa_{n-1, m-1}, \frac{\lambda}{\lambda+s} \kappa_{0}\right) h_{n, m}(0, x) .
\end{aligned}
$$

Therefore, by definition it holds $\kappa_{n, m} \leq \max \left(\kappa_{n-1, m-1}, \frac{\lambda}{\lambda+s} \kappa_{0}\right), 0<m \leq n$, which provides a contradiction as at the end of the proof of Lemma 2.1.

Lemma 3.2 Let $h_{n, m}^{*}(s, x)$ be arbitrary continuous functions such that

$$
\begin{equation*}
0 \leq h_{n, m}^{*}(s, x) \leq h_{n, m}^{*}(0, x), \quad 0<m \leq n, 0 \leq x<d, s \in \mathbb{R}_{+} \tag{3.16}
\end{equation*}
$$

Assume that there exists a non negative solution of the system of integral equations (3.13) for $s=0$.

Then the system of integral equations (3.13) has a minimal non negative solution $\tilde{h}_{n, m}(s, x)$ for any $s \in \mathbb{R}_{+}$, and it holds

$$
\begin{equation*}
\tilde{h}_{n, m}(s, x) \leq \tilde{h}_{n, m}(0, x), \quad 0<m \leq n, 0 \leq x<d, s \in \mathbb{R}_{+} \tag{3.17}
\end{equation*}
$$

Proof For fixed $s \in \mathbb{R}_{+}$let $h_{n, m ; 0}(s, x):=0,0<m \leq n, 0 \leq x<d$, and recursively for $i=0,1, \ldots$ let

$$
\begin{gather*}
h_{n, m ; i+1}(s, x):=h_{n, m}^{*}(s, x)+\frac{1}{\varphi(n)} \int_{0}^{x}\left(\mathbb{I}\{m>1\} \lambda h_{n-1, m-1 ; i}(s, \xi)\right. \\
\left.+\varphi(n+1) m \mu h_{n+1, m+1 ; i}(s, \xi)+\varphi(n+1) h_{n+1, m ; i}(s, \xi)\right) \\
e^{-\left(\frac{\lambda+s}{\varphi(n)}+n \mu\right)(x-\xi)} \mathrm{d} \xi, \quad 0<m \leq n, 0 \leq x<d \tag{3.18}
\end{gather*}
$$

By induction on $i \in \mathbb{Z}_{+}$after some algebra it follows that $h_{n, m ; i}(s, x)$ is monotonically increasing with respect to $i$, that

$$
\begin{equation*}
h_{n, m ; i}(s, x) \leq h_{n, m}(s, x), \quad 0<m \leq n, 0 \leq x<d \tag{3.19}
\end{equation*}
$$

for any non negative solution $h_{n, m}(s, x)$ of (3.13), and that

$$
\begin{equation*}
h_{n, m ; i}(s, x) \leq h_{n, m}(0, x), \quad 0<m \leq n, 0 \leq x<d \tag{3.20}
\end{equation*}
$$

for any non negative solution $h_{n, m}(0, x)$ of (3.13) for $s=0$. Thus the limit

$$
\tilde{h}_{n, m}(s, x):=\lim _{i \rightarrow \infty} h_{n, m ; i}(s ; x), \quad 0<m \leq n, 0 \leq x<d,
$$

exists pointwise and represents, due to (3.18) and Lebesgue's theorem, a non negative solution of (3.13). From (3.19) it follows that $\tilde{h}_{n, m}(s, x)$ is the minimal non negative solution of (3.13), and (3.20) implies (3.17).

Now, from Theorem 2.3, and Lemma 3.1, Lemma 3.2 we obtain the following

Theorem 3.1 Let the stability condition (1.1) for the $M / G I / S D P S$ system, where the service time distribution fulfills (3.1), be satisfied. Then for $s \in \mathbb{R}_{+}$and $\tau \in[0, d)$ the LSTs of $V(n, \tau)$, $n \in \mathbb{Z}_{+}$, and $V(\tau)$ are given by

$$
\begin{array}{ll}
E\left[e^{-s V(n, \tau)}\right]=\frac{\varphi(n+1)}{\lambda(\tau) p(n)} \sum_{m=1}^{n+1} g_{n+1, m}(s, \tau), & \tau \in[0, d) \\
E\left[e^{-s V(\tau)}\right]=\frac{1}{\lambda(\tau)} \sum_{n=1}^{\infty} \varphi(n) \sum_{m=1}^{n} g_{n, m}(s, \tau), \quad \tau \in[0, d) \tag{3.22}
\end{array}
$$

respectively, where

$$
\begin{equation*}
\lambda(x)=\lambda e^{-\mu x}, \quad x \in[0, d) \tag{3.23}
\end{equation*}
$$

$g_{n, m}(s, x)$ is given by (3.8), (3.9), and $h_{n, m}(s, x)$ is the minimal non negative solution of the linear system of ODEs (3.10) with initial condition (3.11).

Proof Suppose that (3.1) and (A1) are fulfilled. Then Theorem 2.3 provides $(3.21),(3.22),(3.23)$, where $g_{n, m}(s, x)$ is given by (3.8), (3.9), and $h_{n, m}(s, x)$ is a solution of the linear system of ODEs (3.10) with initial condition (3.11). Further, taking into account (3.8), we find that $h_{n, m}(s, x)$ is non negative and monotonically decreasing with respect to $s \in \mathbb{R}_{+}$since $g_{n, m}(s, x)$ is non negative and monotonically decreasing with respect to $s \in \mathbb{R}_{+}$in view of (2.26). The case of a general distribution $B(x)$ of the service time with finite mean $m_{S}$ and (3.1) is obtained by taking for fixed $\tau \in[0, d)$ the limit in distribution of a sequence of service time distributions $B_{\nu}(x), \nu=1,2, \ldots$, where the service times have the given mean $m_{S}, B_{\nu}(x)$ is given by (3.1) for $x \in\left[0, d^{\prime}\right)$ for some $d^{\prime} \in(\tau, d)$, the $B_{\nu}(x)$ fulfill (A1) and converge weakly to $B(x)$.

As $h_{n, m}(0, x)$ given by (3.12) is a non negative solution of (3.10), (3.11) for $s=0$, in view of (3.14) from Lemma 3.2 it follows that there exists a
minimal non negative solution $\tilde{h}_{n, m}(s, x)$ of (3.10), (3.11), and that it holds $0 \leq \tilde{h}_{n, m}(s, x) \leq \tilde{h}_{n, m}(0, x) \leq h_{n, m}(0, x)$. Since $h_{n, m}(s, x)$ is non negative and monotonically decreasing with respect to $s \in \mathbb{R}_{+}$, moreover it holds $0 \leq h_{n, m}(s, x) \leq h_{n, m}(0, x)$. In view of Lemma 3.1 for $c=1$, thus we have $h_{n, m}(s, x)=\widetilde{h}_{n, m}(s, x)$ for $s \in(0, \infty)$.

As $h_{n, m}(s, x)$ is monotonically decreasing with respect to $s \in \mathbb{R}_{+}$, the limit

$$
h_{n, m}(x):=\lim _{s \downarrow 0} h_{n, m}(s, x)=\lim _{s \downarrow 0} \tilde{h}_{n, m}(s, x), \quad 0<m \leq n, 0 \leq x<d,
$$

exists pointwise and represents, due to Lebesgue's theorem, a non negative solution of (3.13) for $s=0$, and it holds $\tilde{h}_{n, m}(0, x) \leq h_{n, m}(x)$ as $\tilde{h}_{n, m}(0, x)$ is the minimal non negative solution of (3.13) for $s=0$. Further, Lemma 3.2 provides that $\tilde{h}_{n, m}(s, x) \leq \tilde{h}_{n, m}(0, x)$ for $s \in(0, \infty)$, and by taking the limit $s \downarrow 0$ we find $h_{n, m}(x) \leq \tilde{h}_{n, m}(0, x)$. Hence we have $h_{n, m}(x)=\tilde{h}_{n, m}(0, x)$.

Note that $\lim _{s \downarrow 0} E\left[e^{-s V(n, \tau)}\right]=1$ since the distribution of $V(n, \tau)$ is non defective because of the stability of the system. Taking the limit $s \downarrow 0$ in (3.21) therefore provides

$$
\sum_{m=1}^{n} d_{n-m}(x) h_{n, m}(x)=\frac{\lambda(x) p(n-1)}{\varphi(n)}, \quad 0<n, 0 \leq x<d,
$$

cf. (3.8). On the other hand, from (3.9), (3.12), (3.23), (1.2) we find

$$
\sum_{m=1}^{n} d_{n-m}(x) h_{n, m}(0, x)=\frac{\lambda(x) p(n-1)}{\varphi(n)}, \quad 0<n, 0 \leq x<d
$$

In view of $h_{n, m}(x)=\tilde{h}_{n, m}(0, x) \leq h_{n, m}(0, x)$ and $d_{n-m}(x)>0$, therefore we conclude that

$$
\begin{equation*}
\lim _{s \downarrow 0} h_{n, m}(s, x)=\tilde{h}_{n, m}(0, x)=h_{n, m}(0, x) . \tag{3.24}
\end{equation*}
$$

Thus $h_{n, m}(0, x)$ given by (3.12) is the minimal non negative solution of (3.10), (3.11) for $s=0$.

Remark 3.1 Note that the data in (3.10)-(3.12) are independent of $m_{S}$ and thus of $B(\xi)$ for $\xi \geq d$, and therefore $h_{n, m}(s, x)$ as the minimal non negative solution of (3.10), (3.11) is independent of $B(\xi)$ for $\xi \geq d$, too. Moreover, $h_{n, m}(s, x)$ can be continued for fixed $s \in \mathbb{R}_{+}$to the minimal non negative solution of (3.10), (3.11) for $x \in \mathbb{R}_{+}$since the proof of Lemma 3.2 remains valid for any positive $d$.

For $s \in(0, \infty), \ell \in \mathbb{Z}_{+}$let

$$
\begin{equation*}
h_{n, m}^{(\ell)}(s, x):=(-1)^{\ell} \frac{\partial^{\ell}}{\partial s^{\ell}} h_{n, m}(s, x), \quad 0<m \leq n, 0 \leq x<d . \tag{3.25}
\end{equation*}
$$

Note that from (2.30), (3.8) it follows

$$
\begin{equation*}
g_{n, m}^{(\ell)}(s, x)=d_{n-m}(x) h_{n, m}^{(\ell)}(s, x), \quad 0<m \leq n, 0 \leq x<d . \tag{3.26}
\end{equation*}
$$

Thus $h_{n, m}^{(\ell)}(s, x)$ is monotonically decreasing with respect to $s \in(0, \infty)$ in view of (2.31), and (2.32) implies

$$
\begin{equation*}
0 \leq h_{n, m}^{(\ell)}(s, x) \leq \ell!s^{-\ell} h_{n, m}(0, x), \quad 0<m \leq n, 0 \leq x<d . \tag{3.27}
\end{equation*}
$$

Taking the $\ell$ th derivative with respect to $s \in(0, \infty)$ at both sides of (3.10) provides the linear system of ODEs

$$
\begin{align*}
& \varphi(n) \frac{\partial}{\partial x} h_{n, m}^{(\ell)}(s, x)=-(\lambda+s+\varphi(n) n \mu) h_{n, m}^{(\ell)}(s, x) \\
& \quad+\mathbb{I}\{m>1\} \lambda h_{n-1, m-1}^{(\ell)}(s, x)+\varphi(n+1) m \mu h_{n+1, m+1}^{(\ell)}(s, x) \\
& \quad+\varphi(n+1) h_{n+1, m}^{(\ell)}(s, x)+\ell h_{n, m}^{(\ell-1)}(s, x), \quad 0<m \leq n, 0<x<d, \tag{3.28}
\end{align*}
$$

where $h_{n, m}^{(-1)}(s, x):=0$, and from (3.11) we obtain the initial condition

$$
\begin{equation*}
h_{n, m}^{(\ell)}(s, 0)=\mathbb{I}\{\ell=0, m=1\} \prod_{j=1}^{n} \frac{\lambda}{\varphi(j)}, \quad 0<m \leq n . \tag{3.29}
\end{equation*}
$$

Note that the system of ODEs (3.28) with initial condition (3.29) is equivalent to the following system of integral equations:

$$
\begin{gather*}
h_{n, m}^{(\ell)}(s, x)=h_{n, m}^{*}(s, x)+\frac{1}{\varphi(n)} \int_{0}^{x}\left(\mathbb{I}\{m>1\} \lambda h_{n-1, m-1}^{(\ell)}(s, \xi)\right. \\
\left.+\varphi(n+1) m \mu h_{n+1, m+1}^{(\ell)}(s, \xi)+\varphi(n+1) h_{n+1, m}^{(\ell)}(s, \xi)\right) \\
e^{-\left(\frac{\lambda+s}{\varphi(n)}+n \mu\right)(x-\xi)} \mathrm{d} \xi, \quad 0<m \leq n, 0 \leq x<d, \tag{3.30}
\end{gather*}
$$

where

$$
\begin{align*}
& h_{n, m}^{*}(s, x)=\mathbb{I}\{\ell=0, m=1\}\left(\prod_{j=1}^{n} \frac{\lambda}{\varphi(j)}\right) e^{-\left(\frac{\lambda+s}{\varphi(n)}+n \mu\right) x} \\
& \quad+\frac{\ell}{\varphi(n)} \int_{0}^{x} h_{n, m}^{(\ell-1)}(s, \xi) e^{-\left(\frac{\lambda+s}{\varphi(n)}+n \mu\right)(x-\xi)} \mathrm{d} \xi, \quad 0<m \leq n, 0 \leq x<d . \tag{3.31}
\end{align*}
$$

Assume now that (2.37) is fulfilled for some fixed $k \in \mathbb{N}$. Due to Hölder's inequality and Theorem 2.3, then the limits

$$
g_{n, m}^{(\ell)}(x)=\lim _{s \downarrow 0} g_{n, m}^{(\ell)}(s, x), \quad 0<m \leq n, 0 \leq x<d,
$$

cf. (2.33), exist for $\ell=0,1, \ldots, k$. In view of (3.26), thus also the limits

$$
\begin{equation*}
h_{n, m}^{(\ell)}(x):=\lim _{s \downarrow 0} h_{n, m}^{(\ell)}(s, x), \quad 0<m \leq n, 0 \leq x<d, \tag{3.32}
\end{equation*}
$$

exist for $\ell=0,1, \ldots, k$, and it holds

$$
\begin{equation*}
g_{n, m}^{(\ell)}(x)=d_{n-m}(x) h_{n, m}^{(\ell)}(x), \quad 0<m \leq n, 0 \leq x<d, \tag{3.33}
\end{equation*}
$$

for $\ell=0,1, \ldots, k$. Taking the limit $s \downarrow 0$ in (3.28) and (3.29) provides the linear systems of ODEs

$$
\begin{gather*}
\varphi(n) \frac{\mathrm{d}}{\mathrm{~d} x} h_{n, m}^{(\ell)}(x)=-(\lambda+\varphi(n) n \mu) h_{n, m}^{(\ell)}(x)+\mathbb{I}\{m>1\} \lambda h_{n-1, m-1}^{(\ell)}(x) \\
+\varphi(n+1) m \mu h_{n+1, m+1}^{(\ell)}(x)+\varphi(n+1) h_{n+1, m}^{(\ell)}(x)+\ell h_{n, m}^{(\ell-1)}(x), \\
0<m \leq n, 0<x<d, \ell \in\{1, \ldots, k\}, \tag{3.34}
\end{gather*}
$$

with the initial conditions

$$
\begin{equation*}
h_{n, m}^{(\ell)}(0)=0, \quad 0<m \leq n, \ell \in\{1, \ldots, k\} \tag{3.35}
\end{equation*}
$$

In view of (3.32), (3.25), from (3.24) and (3.12) we find

$$
\begin{equation*}
h_{n, m}^{(0)}(x)=\left(\prod_{j=1}^{n} \frac{\lambda}{\varphi(j)}\right) e^{-n \mu x} \frac{F^{m-1}(x)}{(m-1)!}, \quad 0<m \leq n, 0 \leq x<d \tag{3.36}
\end{equation*}
$$

Now, from Theorem 2.3, and Lemma 3.1, Lemma 3.2 we obtain the following
Theorem 3.2 Let the stability condition (1.1) for the M/GI/SDPS system, where the service time distribution fulfills (3.1), be satisfied. Further, let (2.37) be fulfilled for some $k \in \mathbb{N}$. Then the $k$ th moments of $V(n, \tau)$, $n \in \mathbb{Z}_{+}$, and $V(\tau)$ are finite for $\tau \in \mathbb{R}_{+}$, and for $\tau \in[0, d)$ it holds

$$
\begin{array}{ll}
E\left[V^{k}(n, \tau)\right]=\frac{\varphi(n+1)}{\lambda(\tau) p(n)} \sum_{m=1}^{n+1} g_{n+1, m}^{(k)}(\tau), & \tau \in[0, d) \\
E\left[V^{k}(\tau)\right]=k \int_{0}^{\tau} \sum_{n=1}^{\infty} \sum_{m=1}^{n} \frac{g_{n, m}^{(k-1)}(x)}{\lambda(x)} \mathrm{d} x, & \tau \in[0, d) \tag{3.38}
\end{array}
$$

where $\lambda(x)$ is given by (3.23) and $g_{n, m}^{(\ell)}(x)$ by (3.33), (3.9) for $\ell=0,1, \ldots, k$, where $h_{n, m}^{(0)}(x)$ is given by (3.36) and $h_{n, m}^{(\ell)}(x)$ is the minimal non negative solution of the linear system of ODEs (3.34), (3.35) for $\ell=1, \ldots, k$.

Proof Suppose that (3.1) and (A1) are fulfilled. Then Theorem 2.3 provides $(3.37),(3.38)$, where $\lambda(x)$ is given by $(3.23), g_{n, m}^{(\ell)}(x)$ is given by (3.33), (3.9) for $\ell=0,1, \ldots, k$, where $h_{n, m}^{(0)}(x)$ is given by $(3.36)$ and $h_{n, m}^{(\ell)}(x)$ is defined by (3.32) for $\ell=1, \ldots, k$. The case of a general distribution $B(x)$ of the service time with finite mean $m_{S}$ and (3.1) is obtained by taking for fixed $\tau \in[0, d)$ the limit in distribution of a sequence of service time distributions $B_{\nu}(x), \nu=1,2, \ldots$, where the service times have the given mean $m_{S}, B_{\nu}(x)$ is given by (3.1) for $x \in\left[0, d^{\prime}\right)$ for some $d^{\prime} \in(\tau, d)$, the $B_{\nu}(x)$ fulfill (A1) and converge weakly to $B(x)$.

Let $\ell \in\{1, \ldots, k\}$ be fixed. As $h_{n, m}^{(\ell)}(x)$ is a non negative solution of (3.28), (3.29) for $s=0$, in view of (3.30), (3.31) from Lemma 3.2 it follows that there exists a minimal non negative solution $\tilde{h}_{n, m}^{(\ell)}(s, x)$ of (3.28), (3.29) for any $s \in \mathbb{R}_{+}$, and that it holds $0 \leq \tilde{h}_{n, m}^{(\ell)}(s, x) \leq \tilde{h}_{n, m}^{(\ell)}(0, x)$. From (3.27) we obtain $0 \leq \tilde{h}_{n, m}^{(\ell)}(s, x) \leq h_{n, m}^{(\ell)}(s, x) \leq \ell!s^{-\ell} h_{n, m}(0, x)$ for $s \in(0, \infty)$, which implies $h_{n, m}^{(\ell)}(s, x)=\tilde{h}_{n, m}^{(\ell)}(s, x)$ for $s \in(0, \infty)$ by applying Lemma 3.1 for $c=\ell!s^{-\ell}$. Since the limit

$$
h_{n, m}^{(\ell)}(x)=\lim _{s \downarrow 0} h_{n, m}^{(\ell)}(s, x)=\lim _{s \downarrow 0} \tilde{h}_{n, m}^{(\ell)}(s, x), \quad 0<m \leq n, 0 \leq x<d,
$$

represents, due to Lebesgue's theorem, a non negative solution of (3.30) for $s=0$, we obtain $\tilde{h}_{n, m}^{(\ell)}(0, x) \leq h_{n, m}^{(\ell)}(x)$ as $\tilde{h}_{n, m}^{(\ell)}(0, x)$ is the minimal non negative solution of (3.30) for $s=0$. Further, as $\tilde{h}_{n, m}^{(\ell)}(s, x) \leq \tilde{h}_{n, m}^{(\ell)}(0, x)$ for $s \in(0, \infty)$, by taking the limit $s \downarrow 0$ we find $h_{n, m}^{(\ell)}(x) \leq \tilde{h}_{n, m}^{(\ell)}(0, x)$. Hence it holds $h_{n, m}^{(\ell)}(x)=\tilde{h}_{n, m}^{(\ell)}(0, x)$. Thus $h_{n, m}^{(\ell)}(x)$ is the minimal non negative solution of $(3.28),(3.29)$ for $s=0$, i.e. of (3.34), (3.35).

Note that the LSTs and the moments of $V(n, \tau), n \in \mathbb{Z}_{+}$, and $V(\tau)$ at $\tau=d$ are given by continuous continuation from $0 \leq \tau<d$.

### 3.1 Cut exponential service times

Let the service times be distributed according to the minimum of an exponential time with parameter $\mu \in \mathbb{R}_{+}$and a deterministic time $d \in(0, \infty)$, i.e.

$$
\begin{equation*}
B(x)=1-\mathbb{I}\{0 \leq x<d\} e^{-\mu x}, \quad x \in \mathbb{R}_{+} . \tag{3.39}
\end{equation*}
$$

For the mean $m_{S}$ we find

$$
\begin{equation*}
m_{S}=e^{-\mu d} F(d), \tag{3.40}
\end{equation*}
$$

where $F(d)$ is given by (3.6). Note that the model corresponds to an $M / D / S D P S$ system for $\mu=0$.

Let the stability condition (1.1) for the $M / G I / S D P S$ system with service time distribution (3.39) be satisfied. Then the LSTs of $V(n, \tau), n \in \mathbb{Z}_{+}$, and $V(\tau), \tau \in[0, d)$, are given by Theorem 3.1, and the moments of $V(n, \tau)$, $n \in \mathbb{Z}_{+}$, and $V(\tau), \tau \in[0, d)$, are given by Theorem 3.2.

In view of

$$
E\left[e^{-s V}\right]=\int_{\mathbb{R}_{+}} E\left[e^{-s V(\tau)}\right] \mathrm{d} B(\tau), \quad E\left[V^{k}\right]=\int_{\mathbb{R}_{+}} E\left[V^{k}(\tau)\right] \mathrm{d} B(\tau),
$$

and (3.23), (3.39), (3.40), from Theorem 3.1 and Theorem 3.2 we obtain the following representations for the LST and the moments of the unconditional sojourn time $V$, respectively, where (1.7) and Fubini's theorem are used for the moments of $V$.

Theorem 3.3 Let the stability condition (1.1) for the M/GI/SDPS system with service time distribution (3.39) be satisfied. Then for $s \in(0, \infty)$, the $L S T$ of $V$ is given by

$$
\begin{equation*}
E\left[e^{-s V}\right]=\frac{1}{\lambda} \sum_{n=1}^{\infty} \varphi(n) \sum_{m=1}^{n}\left(\mu \int_{0}^{d} g_{n, m}(s, x) \mathrm{d} x+g_{n, m}(s, d-)\right), \tag{3.41}
\end{equation*}
$$

where $g_{n, m}(s, x)$ is given by (3.8), (3.9), and $h_{n, m}(s, x)$ is the minimal non negative solution of the linear system of ODEs (3.10) with initial condition (3.11). If additionally (2.37) is fulfilled for some $k \in \mathbb{N}$, then the $k$ th moment of $V$ is finite, and it holds

$$
\begin{equation*}
E\left[V^{k}\right]=\frac{k}{\lambda} \int_{0}^{d} \sum_{n=1}^{\infty} \sum_{m=1}^{n} g_{n, m}^{(k-1)}(x) \mathrm{d} x, \tag{3.42}
\end{equation*}
$$

where $g_{n, m}^{(k-1)}(x)$ is given by (3.33), (3.9), where $h_{n, m}^{(0)}(x)$ is given by (3.36) and $h_{n, m}^{(\ell)}(x)$ is the minimal non negative solution of the linear system of ODEs (3.34), (3.35) for $\ell=1, \ldots, k-1$.

### 3.2 Numerical results

We apply the results of this section to the variance of the sojourn time $V$ in $M / D / r-P S$, which means $\mu=0$ in (3.39) and $\varphi(n)=\min (r / n, 1)$, $n \in \mathbb{N}$. Let the stability condition (1.1) for the $M / D / r-P S$ system be satisfied, i.e., let $\varrho=\lambda d<r$. Then (2.37) is fulfilled for all $k \in \mathbb{N}$. Thus from Theorem 3.3 it follows that $E\left[V^{2}\right]$ in $M / D / r-P S$ is given by (3.42) for $k=2$, where $g_{n, m}^{(1)}(x)$ is given by (3.33), (3.9) for $\ell=1$, where $h_{n, m}^{(1)}(x)$ is the minimal non negative solution of the linear system of ODEs (3.34) with the initial condition (3.35) for $\ell=1$, and $h_{n, m}^{(0)}(x)$ is given by (3.36). In view of $\mu=0$, from (3.33), (3.9), (3.40), (3.6), (3.34), (3.36), and (3.35) we obtain that

$$
\begin{equation*}
g_{n, m}^{(1)}(x)=p(0) \frac{(d-x)^{n-m}}{(n-m)!} h_{n, m}^{(1)}(x), \quad 0<m \leq n, 0 \leq x<d, \tag{3.43}
\end{equation*}
$$

where $h_{n, m}^{(1)}(x)$ is the minimal non negative solution of the linear system of ODEs

$$
\begin{align*}
& \varphi(n) \frac{\mathrm{d}}{\mathrm{~d} x} h_{n, m}^{(1)}(x)=-\lambda h_{n, m}^{(1)}(x)+\mathbb{I}\{m>1\} \lambda h_{n-1, m-1}^{(1)}(x) \\
&+\varphi(n+1) h_{n+1, m}^{(1)}(x)+\left(\prod_{j=1}^{n} \frac{\lambda}{\varphi(j)}\right) \frac{x^{m-1}}{(m-1)!} \\
& 0<m \leq n, 0<x<d \tag{3.44}
\end{align*}
$$

with the initial condition

$$
\begin{equation*}
h_{n, m}^{(1)}(0)=0, \quad 0<m \leq n . \tag{3.45}
\end{equation*}
$$

The minimal non negative solution $h_{n, m}^{(1)}(x), 0<m \leq n$, of (3.44), (3.45) can be approximated by solving a suitable finite version $n \leq n^{\prime}$ of the linear system of ODEs (3.44), (3.45), where $h_{n, m}^{(1)}(x)$ is replaced by 0 on the r.h.s. of (3.44) if $n>n^{\prime}$. The second moment $E\left[V^{2}\right]$ can be computed subsequently via (3.42), (3.43) by numerical integration. The first moment $E[V]$ can be computed via Little's law (1.5).

Note that the sequence of the solutions of the finite versions of (3.44), (3.45) indexed by $n^{\prime}$ converges pointwise monotonically increasing to $h_{n, m}^{(1)}(x)$ for $n^{\prime} \rightarrow \infty$ : Applying the construction of the minimal non negative solution given in the proof of Lemma 3.2 to the corresponding finite versions of (3.30), (3.31) for $s=0$ and $\ell=1$, by induction on $i \in \mathbb{Z}_{+}$and taking then the limit $i \rightarrow \infty$ we obtain the monotonicity of the solutions of the finite versions of
(3.30), (3.31) with respect to $n^{\prime}$ and that they are bounded by $h_{n, m}^{(1)}(x)$. Thus the sequence of these solutions converges pointwise monotonically increasing to a non negative solution of (3.30), (3.31), which is bounded by $h_{n, m}^{(1)}(x)$. Since $h_{n, m}^{(1)}(x)$ is the minimal non negative solution of (3.30), (3.31), the assertion is proved. Therefore, due to Lebesgue's theorem, $E\left[V^{2}\right]$ can be computed with arbitrary accuracy by choosing $n^{\prime}$ sufficiently large.

In Table 3.1 there are given $E V$ and $\operatorname{var}(V)$ for $r=2,4,8,16$. Note that in case of $r=2$ the simple expression (4.54) for $\operatorname{var}(V)=\operatorname{var}(V(d))$ has been used. Without loss of generality we have chosen $d:=1$ (unit of time).

Table 3.1: The mean and variance of the sojourn time $V$ in $M / D / r-P S$ for $r=2,4,8,16$ in case of $d=1$.

| $\varrho / r$ | $r=2$ |  | $r=4$ |  | $r=8$ |  | $r=16$ |  |
| :---: | ---: | ---: | ---: | ---: | ---: | ---: | ---: | ---: |
|  | $E V$ | $\operatorname{var}(V)$ | $E V$ | $\operatorname{var}(V)$ | $E V$ | $\operatorname{var}(V)$ | $E V$ | $\operatorname{var}(V)$ |
| 0.30 | 1.0989 | 0.0559 | 1.0132 | 0.0034 | 1.0006 | 0.0001 | 1.0000 | 0.0000 |
| 0.35 | 1.1396 | 0.0885 | 1.0232 | 0.0070 | 1.0017 | 0.0002 | 1.0000 | 0.0000 |
| 0.40 | 1.1905 | 0.1354 | 1.0378 | 0.0133 | 1.0039 | 0.0006 | 1.0001 | 0.0000 |
| 0.45 | 1.2539 | 0.2031 | 1.0584 | 0.0239 | 1.0079 | 0.0014 | 1.0004 | 0.0000 |
| 0.50 | 1.3333 | 0.3011 | 1.0870 | 0.0411 | 1.0148 | 0.0033 | 1.0011 | 0.0001 |
| 0.55 | 1.4337 | 0.4454 | 1.1260 | 0.0689 | 1.0260 | 0.0069 | 1.0029 | 0.0003 |
| 0.60 | 1.5625 | 0.6628 | 1.1794 | 0.1142 | 1.0436 | 0.0140 | 1.0065 | 0.0009 |
| 0.65 | 1.7316 | 1.0018 | 1.2532 | 0.1889 | 1.0708 | 0.0274 | 1.0137 | 0.0025 |
| 0.70 | 1.9608 | 1.5563 | 1.3572 | 0.3166 | 1.1128 | 0.0529 | 1.0270 | 0.0063 |
| 0.75 | 2.2857 | 2.5273 | 1.5094 | 0.5476 | 1.1785 | 0.1030 | 1.0511 | 0.0151 |
| 0.80 | 2.7778 | 4.4060 | 1.7455 | 1.0045 | 1.2860 | 0.2083 | 1.0953 | 0.0366 |
| 0.85 | 3.6036 | 8.6560 | 2.1489 | 2.0534 | 1.4771 | 0.4604 | 1.1805 | 0.0933 |
| 0.90 | 5.2632 | 21.3348 | 2.9694 | 5.2085 | 1.8769 | 1.2376 | 1.3696 | 0.2797 |
| 0.95 | 10.2564 | 92.7299 | 5.4571 | 23.0418 | 3.1104 | 5.6830 | 1.9752 | 1.3814 |

## $4 M / G I / r-P S$ with locally exponential service times

We consider now an $M / G I / r-P S$ system, i.e.

$$
\begin{equation*}
\varphi(n)=\min (r / n, 1), \quad n \in \mathbb{N} \tag{4.1}
\end{equation*}
$$

where the service time $S$ has finite mean $m_{S}$ and its distribution $B(x)$ coincides with an exponential distribution in a neighborhood of zero, i.e.

$$
\begin{equation*}
B(x)=1-e^{-\mu x}, \quad x \in[0, d) \tag{4.2}
\end{equation*}
$$

where $\mu \in(0, \infty)$, for some $d \in(0, \infty)$. Moreover, we assume that the stability condition (1.1) is satisfied, i.e. that $\varrho<r$, and that the system is in steady state. From Theorem 3.1 it follows that the LST of $V(\tau)$ for $s \in(0, \infty)$ is given by

$$
\begin{array}{r}
E\left[e^{-s V(\tau)}\right]=\frac{e^{\mu \tau}}{\lambda} \sum_{n=1}^{\infty} \varphi(n) \sum_{m=1}^{n} \frac{p(0)}{(n-m)!}\left(m_{S} e^{\mu \tau}-F(\tau)\right)^{n-m} h_{n, m}(s, \tau) \\
\tau \in[0, d) \tag{4.3}
\end{array}
$$

where $h_{n, m}(s, x)$ is the minimal non negative solution of the linear system of ODEs (3.10) with initial condition (3.11). Applying the substitution

$$
\begin{align*}
& h_{n, m}(s, x)=\lambda^{n+1-m}\left(\prod_{j=1}^{n} \frac{1}{\varphi(j)}\right) e^{-\mu x} \vartheta_{n, m}(s / \lambda, \lambda x) \\
& 0<m \leq n, 0 \leq x<d \tag{4.4}
\end{align*}
$$

and the notation $\kappa:=\mu / \lambda$, it follows that $\vartheta_{n, m}(\sigma, \xi)$ is the minimal non negative solution of

$$
\begin{align*}
& \frac{\partial}{\partial \xi} \vartheta_{n, m}(\sigma, \xi)=-\left(\frac{1+\sigma}{\varphi(n)}+(n-1) \kappa\right) \vartheta_{n, m}(\sigma, \xi) \\
& \quad+\mathbb{I}\{m>1\} \vartheta_{n-1, m-1}(\sigma, \xi)+\frac{m \kappa}{\varphi(n)} \vartheta_{n+1, m+1}(\sigma, \xi) \\
& \quad+\frac{1}{\varphi(n)} \vartheta_{n+1, m}(\sigma, \xi), \quad 0<m \leq n, \xi \in(0, \infty) \tag{4.5}
\end{align*}
$$

with initial condition

$$
\begin{equation*}
\vartheta_{n, m}(\sigma, 0)=\mathbb{I}\{m=1\}, \quad 0<m \leq n \tag{4.6}
\end{equation*}
$$

restricted to $\xi \in[0, \lambda d)$, cf. Remark 3.1. The linear system of ODEs (4.5), (4.6) is equivalent to the system of integral equations

$$
\begin{align*}
& \vartheta_{n, m}(\sigma, \xi)=\mathbb{I}\{m=1\} e^{-\left(\frac{1+\sigma}{\varphi(n)}+(n-1) \kappa\right) \xi} \\
& \quad+\int_{0}^{\xi}\left(\mathbb{I}\{m>1\} \vartheta_{n-1, m-1}(\sigma, \eta)+\frac{m \kappa}{\varphi(n)} \vartheta_{n+1, m+1}(\sigma, \eta)\right. \\
& \\
& \left.\quad+\frac{1}{\varphi(n)} \vartheta_{n+1, m}(\sigma, \eta)\right) e^{-\left(\frac{1+\sigma}{\varphi(n)}+(n-1) \kappa\right)(\xi-\eta)} \mathrm{d} \eta  \tag{4.7}\\
& \\
& \quad 0<m \leq n, \xi \in \mathbb{R}_{+}
\end{align*}
$$

As $\left(e^{-(n-1) \kappa \xi} /(m-1)!\right)\left(\left(e^{\kappa \xi}-1\right) / \kappa\right)^{m-1}, 0<m \leq n, \xi \in \mathbb{R}_{+}$, is a non negative solution of (4.5), (4.6) for $\sigma=0$, the minimal non negative solution $\vartheta_{n, m}(\sigma, \xi), 0<m \leq n, \xi \in \mathbb{R}_{+}$, of (4.7) for $\sigma>0$ can be constructed by the method of successive approximation starting from $\vartheta_{n, m ; 0}(\sigma, \xi) \equiv 0$, defining $\vartheta_{n, m ; i+1}(\sigma, \xi)$ recursively with respect to $i$ by the r.h.s. of (4.7), where the $\vartheta_{n^{\prime}, m^{\prime}}(\sigma, \eta)$ are replaced by $\vartheta_{n^{\prime}, m^{\prime} ; i}(\sigma, \eta)$, and taking the limit $i \rightarrow \infty$. This construction provides the estimate

$$
\begin{equation*}
0 \leq \vartheta_{n, m}(\sigma, \xi) \leq \frac{e^{-(n-1) \kappa \xi}}{(m-1)!}\left(\frac{e^{\kappa \xi}-1}{\kappa}\right)^{m-1}, \quad 0<m \leq n, \xi \in \mathbb{R}_{+} \tag{4.8}
\end{equation*}
$$

and it follows that $\vartheta_{n, m}(\sigma, \xi)$ for $0<m \leq n-(r-1)$ does not depend on $\varphi(\ell)$ for $\ell<r$. By continuous continuation from (2.34), (2.36), (4.2), (2.27), (2.28), (3.7), and (4.4) we obtain that

$$
\begin{equation*}
E\left[e^{-\lambda \sigma V(0, \xi / \lambda)}\right]=\vartheta_{1,1}(\sigma, \xi), \quad \xi \in[0, \lambda d] \tag{4.9}
\end{equation*}
$$

where $V(0, \tau)$ denotes the sojourn time of a $\tau$-request finding at its arrival the $M / G I / r-P S$ system empty. Further, by continuous continuation from (4.3), (4.4), and (3.6) we find that

$$
\begin{array}{r}
E\left[e^{-\lambda \sigma V(\xi / \lambda)}\right]=p(0) \sum_{m=1}^{\infty} \sum_{n=m}^{\infty}\left(\prod_{j=1}^{n-1} \frac{1}{\varphi(j)}\right)\left(\frac{(\kappa \varrho-1) e^{\kappa \xi}+1}{\kappa}\right)^{n-m} \\
\frac{\vartheta_{n, m}(\sigma, \xi)}{(n-m)!}, \quad \xi \in[0, \lambda d] \tag{4.10}
\end{array}
$$

Note that $\varrho=1 / \kappa$ for the $M / M / r-P S$ system.
As $\vartheta_{n, m}(\sigma, \xi)$ for $0<m \leq n-(r-1)$ does not depend on $\varphi(\ell)$ for $\ell<r$, besides the $M / G I / r-P S$ system we consider the corresponding $M / G I / S D P S$ system where the service capacity $\varphi(n)=\min (r / n, 1), n \in \mathbb{N}$, is replaced by

$$
\begin{equation*}
\tilde{\varphi}(n)=r / n, \quad n \in \mathbb{N} \tag{4.11}
\end{equation*}
$$

Note that this $M / G I / S D P S$ system is equivalent to an $M / G I / 1-P S$ system by replacing the service time $S$ by $S / r$. We denote by $\tilde{p}(n)$ the stationary occupancy distribution of the $M / G I / S D P S$ system with service capacity (4.11), by $\tilde{V}(\tau)$ the sojourn time of a $\tau$-request in this system and by $\tilde{\vartheta}_{n, m}(\sigma, \xi)$ the minimal non negative solution of the corresponding system of ODEs

$$
\frac{\partial}{\partial \xi} \tilde{\vartheta}_{n, m}(\sigma, \xi)=-\left(\frac{1+\sigma}{\tilde{\varphi}(n)}+(n-1) \kappa\right) \tilde{\vartheta}_{n, m}(\sigma, \xi)
$$

$$
\begin{align*}
& +\mathbb{I}\{m>1\} \tilde{\vartheta}_{n-1, m-1}(\sigma, \xi)+\frac{m \kappa}{\tilde{\varphi}(n)} \tilde{\vartheta}_{n+1, m+1}(\sigma, \xi) \\
& +\frac{1}{\tilde{\varphi}(n)} \tilde{\vartheta}_{n+1, m}(\sigma, \xi), \quad 0<m \leq n, \xi \in(0, \infty) \tag{4.12}
\end{align*}
$$

with initial condition

$$
\begin{equation*}
\tilde{\vartheta}_{n, m}(\sigma, 0)=\mathbb{I}\{m=1\}, \quad 0<m \leq n \tag{4.13}
\end{equation*}
$$

which is equivalent to the system of integral equations

$$
\begin{align*}
& \tilde{\vartheta}_{n, m}(\sigma, \xi)=\mathbb{I}\{m=1\} e^{-\left(\frac{1+\sigma}{\tilde{\varphi}(n)}+(n-1) \kappa\right) \xi} \\
& \quad+\int_{0}^{\xi}\left(\mathbb{I}\{m>1\} \tilde{\vartheta}_{n-1, m-1}(\sigma, \eta)+\frac{m \kappa}{\tilde{\varphi}(n)} \tilde{\vartheta}_{n+1, m+1}(\sigma, \eta)\right. \\
& \left.\quad+\frac{1}{\tilde{\varphi}(n)} \tilde{\vartheta}_{n+1, m}(\sigma, \eta)\right) e^{-\left(\frac{1+\sigma}{\tilde{\varphi}(n)}+(n-1) \kappa\right)(\xi-\eta)} \mathrm{d} \eta \\
& 0 \tag{4.14}
\end{align*}
$$

cf. (4.5)-(4.7). Analogously to (4.8) we obtain the estimate

$$
\begin{equation*}
0 \leq \tilde{\vartheta}_{n, m}(\sigma, \xi) \leq \frac{e^{-(n-1) \kappa \xi}}{(m-1)!}\left(\frac{e^{\kappa \xi}-1}{\kappa}\right)^{m-1}, \quad 0<m \leq n, \xi \in \mathbb{R}_{+} \tag{4.15}
\end{equation*}
$$

Further, analogously to (4.9) it follows that

$$
\begin{equation*}
E\left[e^{-\lambda \sigma \tilde{V}(0, \xi / \lambda)}\right]=\tilde{\vartheta}_{1,1}(\sigma, \xi), \quad \xi \in[0, \lambda d] \tag{4.16}
\end{equation*}
$$

where $\tilde{V}(0, \tau)$ denotes the sojourn time of a $\tau$-request finding at its arrival the $M / G I / S D P S$ system with service capacity (4.11) empty. Using the well known expression for the LST of the sojourn time of a $\tau$-request finding at its arrival the corresponding $M / G I / 1-P S$ system with scaled service time empty, cf. [YY1] (2.24) and (2.26), where, because of (4.2), $\psi(s, u)$ for $u \in[0, d)$ can be determined directly from [YY1] (2.22) and the initial condition $\psi(s, 0)=1$, in view of (4.16), after some algebra we obtain that

$$
\begin{align*}
& \tilde{\vartheta}_{1,1}(\sigma, \xi)=E\left[e^{-\lambda \sigma \tilde{V}(0, \xi / \lambda)}\right] \\
& \quad=\frac{r_{2}-r_{1}}{\left(r_{2}-1\right) e^{\left(r_{2}-r \kappa\right) \xi / r}+\left(1-r_{1}\right) e^{\left(r_{1}-r \kappa\right) \xi / r}}, \quad \xi \in[0, \lambda d] \tag{4.17}
\end{align*}
$$

where

$$
\begin{equation*}
r_{1,2}:=\left(1+\sigma+r \kappa \mp \sqrt{(1+\sigma+r \kappa)^{2}-4 r \kappa}\right) / 2 \tag{4.18}
\end{equation*}
$$

are the zeroes of $z^{2}-(1+\sigma+r \kappa) z+r \kappa$. Note that (4.18) implies

$$
\begin{equation*}
0<r_{1}<\min (r \kappa, 1), \quad r_{2}>\max (r \kappa, 1) \tag{4.19}
\end{equation*}
$$

for $\sigma>0$. Moreover, analogously to (4.10) we find that

$$
\begin{array}{r}
E\left[e^{-\lambda \sigma \tilde{V}(\xi / \lambda)}\right]=\tilde{p}(0) \sum_{m=1}^{\infty} \sum_{n=m}^{\infty}\left(\prod_{j=1}^{n-1} \frac{1}{\tilde{\varphi}(j)}\right)\left(\frac{(\kappa \varrho-1) e^{\kappa \xi}+1}{\kappa}\right)^{n-m} \\
\frac{\tilde{\vartheta}_{n, m}(\sigma, \xi)}{(n-m)!}, \quad \xi \in[0, \lambda d] . \tag{4.20}
\end{array}
$$

On the other hand, by using the well known expression for the LST of the sojourn time of a $\tau$-request in the corresponding $M / G I / 1-P S$ system with scaled service time, cf. [YY1] (2.29), in view of (4.2), after some algebra we obtain that

$$
\begin{gather*}
E\left[e^{-\lambda \sigma \tilde{V}(\xi / \lambda)}\right]=\frac{1-\frac{\varrho}{r}}{\frac{\left(1-r_{2}\right)^{2}}{r_{2}\left(r_{2}-r_{1}\right)} e^{\left(r_{2}-r \kappa\right) \xi / r}-\frac{\left(1-r_{1}\right)^{2}}{r_{1}\left(r_{2}-r_{1}\right)} e^{\left(r_{1}-r \kappa\right) \xi / r}+\frac{1-\kappa \varrho}{r \kappa}}, \\
\quad \xi \in[0, \lambda d] . \tag{4.21}
\end{gather*}
$$

Note that (4.21) for $\varrho=1 / \kappa$ also follows from the expression for the LST of the sojourn time of a $\tau$-request in the $M / M / 1-P S$ system, cf. [YY1] (2.43).

As $\vartheta_{n, m}(\sigma, \xi)$ for $0<m \leq n-(r-1)$ does not depend on $\varphi(\ell)$ for $\ell<r$ and since $\varphi(\ell)=\tilde{\varphi}(\ell)$ for $\ell \geq r$, it holds

$$
\begin{equation*}
\vartheta_{n, m}(\sigma, \xi)=\tilde{\vartheta}_{n, m}(\sigma, \xi), \quad 0<m \leq n-(r-1), \xi \in \mathbb{R}_{+} . \tag{4.22}
\end{equation*}
$$

Because of (4.22), (4.1), and (4.11), from (4.10) and (4.20) we obtain that

$$
\begin{align*}
& E\left[e^{-\lambda \sigma V(\xi / \lambda)}\right] \\
& \quad=p(0) \sum_{m=1}^{\infty} \sum_{n=m}^{m+r-2}\left(\prod_{j=1}^{n-1} \frac{1}{\varphi(j)}\right)\left(\frac{(\kappa \varrho-1) e^{\kappa \xi}+1}{\kappa}\right)^{n-m} \frac{\bar{\vartheta}_{n, m}(\sigma, \xi)}{(n-m)!} \\
& \quad-p(0) \sum_{m=1}^{r-1} \sum_{n=m}^{r-1}\left(\left(\prod_{j=n}^{r-1} \frac{r}{j}\right)-1\right)\left(\frac{(\kappa \varrho-1) e^{\kappa \xi}+1}{\kappa}\right)^{n-m} \frac{\tilde{\vartheta}_{n, m}(\sigma, \xi)}{(n-m)!} \\
& \quad+\frac{r^{r} p(0)}{r!\tilde{p}(0)} E\left[e^{-\lambda \sigma \tilde{V}(\xi / \lambda)}\right], \quad \xi \in[0, \lambda d], \tag{4.23}
\end{align*}
$$

where

$$
\begin{equation*}
\bar{\vartheta}_{n, m}(\sigma, \xi):=\vartheta_{n, m}(\sigma, \xi)-\tilde{\vartheta}_{n, m}(\sigma, \xi), \quad 0<m \leq n, \xi \in \mathbb{R}_{+} \tag{4.24}
\end{equation*}
$$

From (4.6) and (4.13) it follows that

$$
\begin{equation*}
\bar{\vartheta}_{n, m}(\sigma, 0)=0, \quad 0<m \leq n, \tag{4.25}
\end{equation*}
$$

and (4.22) provides that

$$
\begin{equation*}
\bar{\vartheta}_{n, m}(\sigma, \xi)=0, \quad 0<m \leq n-(r-1), \xi \in \mathbb{R}_{+} \tag{4.26}
\end{equation*}
$$

Moreover, from (4.8) and (4.15) we find the estimate

$$
\begin{equation*}
\left|\bar{\vartheta}_{n, m}(\sigma, \xi)\right| \leq \frac{e^{-(n-1) \kappa \xi}}{(m-1)!}\left(\frac{e^{\kappa \xi}-1}{\kappa}\right)^{m-1}, \quad 0<m \leq n, \xi \in \mathbb{R}_{+} \tag{4.27}
\end{equation*}
$$

## 4.1 $M / G I / 2-P S$ with locally exponential service times

Let us consider the $M / G I / 2-P S$ system, i.e. the case of $r=2$, in more detail. We assume that the stability condition (1.1) for the $M / G I / 2-P S$ system is satisfied, i.e. that $\varrho<2$, and that the system is in steady state. In view of (1.2), (4.1), (4.11), in case of $r=2$ the representation (4.23) for the LST of the sojourn time of a $\tau$-request simplifies to

$$
\begin{align*}
& E\left[e^{-\lambda \sigma V(\xi / \lambda)}\right]=\frac{1-\varrho / 2}{1+\varrho / 2}\left(2 G(\xi, 1)-G(\xi, 0)-\tilde{\vartheta}_{1,1}(\sigma, \xi)\right) \\
& \quad+\frac{2}{1+\varrho / 2} E\left[e^{-\lambda \sigma \tilde{V}(\xi / \lambda)}\right], \quad \xi \in[0, \lambda d] \tag{4.28}
\end{align*}
$$

where $\tilde{\vartheta}_{1,1}(\sigma, \xi)$ and $E\left[e^{-\lambda \sigma \tilde{V}(\xi / \lambda)}\right]$ are given by (4.17) and (4.21) for $r=2$, respectively, and where for fixed positive $\sigma$

$$
\begin{equation*}
G(\xi, z):=\sum_{m=1}^{\infty} \frac{(m-1)!}{2^{m-1}} \bar{\vartheta}_{m, m}(\sigma, \xi) z^{m-1} \tag{4.29}
\end{equation*}
$$

The series on the r.h.s. of (4.29) converge for $\xi \in[0, \lambda d],|z|<2 / \varrho$ as well as for $\xi \in \mathbb{R}_{+},|z|<2 \kappa$ due to (4.27), (4.2), and it holds

$$
\begin{equation*}
|G(\xi, z)|<\frac{2 \kappa}{2 \kappa-|z|}, \quad \xi \in \mathbb{R}_{+},|z|<2 \kappa \tag{4.30}
\end{equation*}
$$

Further, (4.25) yields that

$$
\begin{equation*}
G(0, z)=0 \tag{4.31}
\end{equation*}
$$

Because of (4.30), the Laplace transform

$$
\begin{equation*}
G^{*}(w, z):=\int_{\mathbb{R}_{+}} e^{-w \xi} G(\xi, z) \mathrm{d} \xi \tag{4.32}
\end{equation*}
$$

of $G(\xi, z)$ with respect to $\xi$ exists for $\Re w>0,|z|<2 \kappa$. From (4.1), (4.5), (4.11), (4.12), (4.24), and (4.26) we find for $\xi \in(0, \infty)$ that

$$
\begin{align*}
& \frac{\partial}{\partial \xi} \bar{\vartheta}_{1,1}(\sigma, \xi)=-(1+\sigma) \bar{\vartheta}_{1,1}(\sigma, \xi)+\kappa \bar{\vartheta}_{2,2}(\sigma, \xi)+\frac{\partial}{\partial \xi} \tilde{\vartheta}_{1,1}(\sigma, \xi)  \tag{4.33}\\
& \frac{\partial}{\partial \xi} \bar{\vartheta}_{m, m}(\sigma, \xi)=-\left(\frac{m(1+\sigma)}{2}+(m-1) \kappa\right) \bar{\vartheta}_{m, m}(\sigma, \xi)+\bar{\vartheta}_{m-1, m-1}(\sigma, \xi) \\
& \quad+\frac{m^{2} \kappa}{2} \bar{\vartheta}_{m+1, m+1}(\sigma, \xi), \quad m \geq 2 \tag{4.34}
\end{align*}
$$

In view of (4.15) and (4.27), the Laplace transform $\tilde{\vartheta}_{1,1}^{*}(\sigma, w)$ of $\tilde{\vartheta}_{1,1}(\sigma, \xi)$ and the Laplace transforms $\bar{\vartheta}_{m, m}^{*}(\sigma, w)$ of $\bar{\vartheta}_{m, m}(\sigma, \xi), m \geq 1$, exist for $\Re w>0$. Because of (4.13) and (4.25), from (4.33) and (4.34) it follows for $\Re w>0$ that

$$
\begin{align*}
& (1+\sigma+w) \bar{\vartheta}_{1,1}^{*}(\sigma, w)=\kappa \bar{\vartheta}_{2,2}^{*}(\sigma, w)+w \tilde{\vartheta}_{1,1}^{*}(\sigma, w)-1  \tag{4.35}\\
& \left(\frac{m(1+\sigma)}{2}+(m-1) \kappa+w\right) \bar{\vartheta}_{m, m}^{*}(\sigma, w)=\bar{\vartheta}_{m-1, m-1}^{*}(\sigma, w) \\
& \quad+\frac{m^{2} \kappa}{2} \bar{\vartheta}_{m+1, m+1}^{*}(\sigma, w), \quad m \geq 2 \tag{4.36}
\end{align*}
$$

respectively. In view of (4.29), (4.32), and (4.35), multiplying both sides of (4.36) by $(m-1)!(z / 2)^{m-1}$ and summing up for $m \geq 2$ provides after some algebra that

$$
\begin{align*}
\left(z^{2}-\right. & (1+\sigma+2 \kappa) z+2 \kappa) \frac{\partial}{\partial z} G^{*}(w, z)+(z-(1+\sigma+2 w)) G^{*}(w, z) \\
& =1-w G^{*}(w, 0)-w \tilde{\vartheta}_{1,1}^{*}(\sigma, w), \quad \Re w>0,|z|<2 \kappa \tag{4.37}
\end{align*}
$$

As the zeroes $r_{1,2}$ of $z^{2}-(1+\sigma+2 \kappa) z+2 \kappa$ fulfill (4.19), $G^{*}(w, z)$ is a solution of the ODE (4.37) for fixed $w$ which is continuous at $z=r_{1}$. For real $z \in\left(r_{1}, 2 \kappa\right)$ thus from (4.37) it follows that

$$
\begin{align*}
& G^{*}(w, z)=\left(w G^{*}(w, 0)+w \tilde{\vartheta}_{1,1}^{*}(\sigma, w)-1\right) \\
& \qquad \int_{r_{1}}^{z}\left(\frac{\left(x-r_{1}\right)\left(r_{2}-z\right)}{\left(z-r_{1}\right)\left(r_{2}-x\right)}\right)^{\frac{r_{2}-2 \kappa+2 w}{r_{2}-r_{1}}} \frac{\mathrm{~d} x}{\left(x-r_{1}\right)\left(r_{2}-z\right)} \\
& \Re w>0, z \in\left(r_{1}, 2 \kappa\right) . \tag{4.38}
\end{align*}
$$

The substitution $\left(\left(x-r_{1}\right)\left(r_{2}-z\right)\right) /\left(\left(z-r_{1}\right)\left(r_{2}-x\right)\right)=e^{-\frac{r_{2}-r_{1}}{2} \xi}$ yields that

$$
\begin{align*}
& G^{*}(w, z)=\frac{r_{2}-r_{1}}{2}\left(w G^{*}(w, 0)+w \tilde{\vartheta}_{1,1}^{*}(\sigma, w)-1\right) \\
& \int_{0}^{\infty} \frac{e^{-w \xi} \mathrm{~d} \xi}{\left(r_{2}-z\right) e^{\left(r_{2}-2 \kappa\right) \xi / 2}+\left(z-r_{1}\right) e^{\left(r_{1}-2 \kappa\right) \xi / 2}} \\
& \quad \Re w>0, z \in\left(r_{1}, 2 \kappa\right) \tag{4.39}
\end{align*}
$$

By means of analytic continuation to $z=0$ and applying the geometric series with common ratio $\left(r_{1} / r_{2}\right) e^{\left(r_{1}-r_{2}\right) \xi / 2}$ to the integrand, for $\Re w>0$ from (4.39) we obtain the representation

$$
\begin{equation*}
G^{*}(w, 0)=\frac{\sum_{k=0}^{\infty} \frac{\left(r_{1} / r_{2}\right)^{k}}{\left(r_{2}-2 \kappa+2 w\right) /\left(r_{2}-r_{1}\right)+k}}{\left.\left.r_{2}-w \sum_{k=0}^{\infty}\left(w \tilde{\vartheta}_{1,1}^{*}(\sigma, w)-1\right)\right) \text { (ri/r}\right)^{k}\left(r_{2}-2 \kappa+2 w\right) /\left(r_{2}-r_{1}\right)+k}\left({ }^{2}\right) \tag{4.40}
\end{equation*}
$$

of the Laplace transform of $G(\xi, 0)$ by a hypergeometric function. On the other hand, in view of (4.13), (4.31), and of the properties of the Laplace transform, from (4.39) we find that

$$
\begin{align*}
& G(\xi, z)=\frac{r_{2}-r_{1}}{2} \int_{0}^{\xi}\left(\frac{\partial}{\partial \eta}\left(G(\eta, 0)+\tilde{\vartheta}_{1,1}(\sigma, \eta)\right)\right) \\
& \frac{\mathrm{d} \eta}{\left(r_{2}-z\right) e^{\left(r_{2}-2 \kappa\right)(\xi-\eta) / 2}+\left(z-r_{1}\right) e^{\left(r_{1}-2 \kappa\right)(\xi-\eta) / 2}}, \\
& \quad \xi \in \mathbb{R}_{+}, z \in\left(r_{1}, 2 \kappa\right), \tag{4.41}
\end{align*}
$$

where (4.41) even holds for $\xi \in \mathbb{R}_{+},|z|<r_{2}$ due to the uniqueness theorem for analytic functions and Taylor's theorem, and where $r_{2}>1$ because of (4.19). In view of (4.13) and (4.31), integration by parts provides that

$$
\begin{align*}
& G(\xi, z)=\frac{1}{2}\left(G(\xi, 0)+\tilde{\vartheta}_{1,1}(\sigma, \xi)\right) \\
& \quad-\frac{1}{2} \frac{r_{2}-r_{1}}{\left(r_{2}-z\right) e^{\left(r_{2}-2 \kappa\right) \xi / 2}+\left(z-r_{1}\right) e^{\left(r_{1}-2 \kappa\right) \xi / 2}} \\
& -\frac{r_{2}-r_{1}}{4} \int_{0}^{\xi}\left(G(\eta, 0)+\tilde{\vartheta}_{1,1}(\sigma, \eta)\right) \\
& \frac{\left(r_{2}-z\right)\left(r_{2}-2 \kappa\right) e^{\left(r_{2}-2 \kappa\right)(\xi-\eta) / 2}+\left(z-r_{1}\right)\left(r_{1}-2 \kappa\right) e^{\left(r_{1}-2 \kappa\right)(\xi-\eta) / 2}}{\left(\left(r_{2}-z\right) e^{\left(r_{2}-2 \kappa\right)(\xi-\eta) / 2}+\left(z-r_{1}\right) e^{\left(r_{1}-2 \kappa\right)(\xi-\eta) / 2}\right)^{2}} \mathrm{~d} \eta, \\
& \quad \xi \in \mathbb{R}_{+},|z|<r_{2} . \quad(4.42) \tag{4.42}
\end{align*}
$$

In particular, choosing $z=0$ in (4.42) yields that

$$
\begin{align*}
& G(\xi, 0)=\tilde{\vartheta}_{1,1}(\sigma, \xi)-\frac{r_{2}-r_{1}}{r_{2} e^{\left(r_{2}-2 \kappa\right) \xi / 2}-r_{1} e^{\left(r_{1}-2 \kappa\right) \xi / 2}} \\
& \quad-\frac{r_{2}-r_{1}}{2} \int_{0}^{\xi}\left(G(\eta, 0)+\tilde{\vartheta}_{1,1}(\sigma, \eta)\right) \\
& \\
& \quad \frac{r_{2}\left(r_{2}-2 \kappa\right) e^{\left(r_{2}-2 \kappa\right)(\xi-\eta) / 2}-r_{1}\left(r_{1}-2 \kappa\right) e^{\left(r_{1}-2 \kappa\right)(\xi-\eta) / 2}}{\left(r_{2} e^{\left(r_{2}-2 \kappa\right)(\xi-\eta) / 2}-r_{1} e^{\left(r_{1}-2 \kappa\right)(\xi-\eta) / 2}\right)^{2}} \mathrm{~d} \eta,  \tag{4.43}\\
&
\end{align*} \quad \xi \in \mathbb{R}_{+} .
$$

Due to (4.43), (4.29), (4.24), (4.9), and (4.17), moreover it holds

$$
\begin{gather*}
E\left[e^{-\lambda \sigma V(0, \xi / \lambda)}\right]=\frac{2\left(r_{2}-r_{1}\right)}{\left(r_{2}-1\right) e^{\left(r_{2}-2 \kappa\right) \xi / 2}+\left(1-r_{1}\right) e^{\left(r_{1}-2 \kappa\right) \xi / 2}} \\
-\frac{r_{2}-r_{1}}{r_{2} e^{\left(r_{2}-2 \kappa\right) \xi / 2}-r_{1} e^{\left(r_{1}-2 \kappa\right) \xi / 2}}-\frac{r_{2}-r_{1}}{2} \int_{0}^{\xi} E\left[e^{-\lambda \sigma V(0, \eta / \lambda)}\right] \\
\frac{r_{2}\left(r_{2}-2 \kappa\right) e^{\left(r_{2}-2 \kappa\right)(\xi-\eta) / 2}-r_{1}\left(r_{1}-2 \kappa\right) e^{\left(r_{1}-2 \kappa\right)(\xi-\eta) / 2}}{\left(r_{2} e^{\left(r_{2}-2 \kappa\right)(\xi-\eta) / 2}-r_{1} e^{\left(r_{1}-2 \kappa\right)(\xi-\eta) / 2}\right)^{2}} \mathrm{~d} \eta, \\
\xi \in[0, \lambda d], \tag{4.44}
\end{gather*}
$$

cf. [Bra] Theorem 4 for the case of an $M / M / 2-P S$ system.
The Volterra integral equation (convolution equation) (4.43) can be used for computing $G(\xi, 0), \xi \in[0, \lambda d]$, e.g. by means of the Neumann series. Alternatively, (4.40) can be used for computing $G(\xi, 0), \xi \in[0, \lambda d]$, by inverting both factors on the r.h.s. and applying the convolution formula. Subsequently, $G(\xi, 1), \xi \in[0, \lambda d]$, can be computed via (4.41) or (4.42) for $z=1$.

## 4.2 $M / G I / 2-P S$ with bounded from below service times

In this section we consider the $M / G I / 2-P S$ system with bounded from below service times, i.e., we consider the case of $r=2$ where

$$
\begin{equation*}
B(x)=0, \quad x \in[0, d), \tag{4.45}
\end{equation*}
$$

for some $d \in(0, \infty)$. Moreover, we assume that the stability condition (1.1) for the $M / G I / 2-P S$ system is satisfied, i.e. that $\varrho<2$, and that the system is in steady state. The LST of $V(\tau)$ is given by the limit $\mu \downarrow 0$ of the LST
of $V(\tau)$ in the corresponding system with locally exponential service times, cf. Section 4.1. Thus from (4.28) we obtain that

$$
\begin{align*}
& E\left[e^{-\lambda \sigma V(\xi / \lambda)}\right]=\lim _{\kappa \downarrow 0}\left(\frac{1-\varrho / 2}{1+\varrho / 2}\left(2 G(\xi, 1)-G(\xi, 0)-\tilde{\vartheta}_{1,1}(\sigma, \xi)\right)\right. \\
& \left.\quad+\frac{2}{1+\varrho / 2} E\left[e^{-\lambda \sigma \tilde{V}(\xi / \lambda)}\right]\right), \quad \xi \in[0, \lambda d] \tag{4.46}
\end{align*}
$$

In view of

$$
\begin{equation*}
\lim _{\kappa \downarrow 0} r_{1}=0, \quad \lim _{\kappa \downarrow 0} r_{2}=1+\sigma \tag{4.47}
\end{equation*}
$$

cf. (4.18), from (4.17) we find that

$$
\begin{equation*}
\lim _{\kappa \downarrow 0} \tilde{\vartheta}_{1,1}(\sigma, \xi)=\frac{1+\sigma}{1+\sigma e^{(1+\sigma) \xi / 2}}, \quad \xi \in[0, \lambda d] \tag{4.48}
\end{equation*}
$$

Moreover, after tedious algebra from (4.21) and (4.18) it follows that

$$
\begin{array}{r}
\lim _{\kappa \downarrow 0} E\left[e^{-\lambda \sigma \tilde{V}(\xi / \lambda)}\right]=\frac{1-\varrho / 2}{(1-\varrho / 2)+\frac{\sigma}{1+\sigma} \xi / 2+\left(\frac{\sigma}{1+\sigma}\right)^{2}\left(e^{(1+\sigma) \xi / 2}-1\right)}, \\
\xi \in[0, \lambda d] \tag{4.49}
\end{array}
$$

In the limiting case of $\kappa \downarrow 0$, in view of (4.47) and (4.48), the Volterra integral equation (4.43) for $G(\xi, 0)$ simplifies to

$$
\begin{align*}
& G(\xi, 0)=\frac{1+\sigma}{1+\sigma e^{(1+\sigma) \xi / 2}}-e^{-(1+\sigma) \xi / 2} \\
& \quad-\frac{1+\sigma}{2} \int_{0}^{\xi}\left(G(\eta, 0)+\frac{1+\sigma}{1+\sigma e^{(1+\sigma) \eta / 2}}\right) e^{-(1+\sigma)(\xi-\eta) / 2} \mathrm{~d} \eta \\
& \xi \in[0, \lambda d] \tag{4.50}
\end{align*}
$$

Multiplying by $e^{(1+\sigma) \xi / 2}$, differentiating with respect to $\xi$, and multiplying again by $e^{(1+\sigma) \xi / 2}$ provides that

$$
\frac{\partial}{\partial \xi}\left(e^{(1+\sigma) \xi} G(\xi, 0)\right)=-\frac{\sigma(1+\sigma)^{2}}{2} \frac{e^{(1+\sigma) 3 \xi / 2}}{\left(1+\sigma e^{(1+\sigma) \xi / 2}\right)^{2}}, \quad \xi \in(0, \lambda d)
$$

In view of $G(0,0)=0$, cf. (4.50), thus we find that

$$
\begin{equation*}
G(\xi, 0)=-\left.\frac{\sigma(1+\sigma)}{\zeta^{2}} \int_{1}^{\zeta}\left(\frac{\eta}{1+\sigma \eta}\right)^{2} \mathrm{~d} \eta\right|_{\zeta=e^{(1+\sigma) \xi / 2}}, \quad \xi \in[0, \lambda d] \tag{4.51}
\end{equation*}
$$

where

$$
\int_{1}^{\zeta}\left(\frac{\eta}{1+\sigma \eta}\right)^{2} \mathrm{~d} \eta=\frac{1}{\sigma^{3}}\left(\sigma(\zeta-1)-2 \log \left(\frac{1+\sigma \zeta}{1+\sigma}\right)+\frac{\sigma(\zeta-1)}{(1+\sigma)(1+\sigma \zeta)}\right)
$$

for $\sigma>0$. Further, in the limiting case of $\kappa \downarrow 0$, taking into account (4.47), (4.48), (4.51), and using integration by parts, from (4.41) for $z=1$ after some algebra we obtain that

$$
\begin{align*}
G(\xi, 1) & =\frac{\sigma(1+\sigma)^{2}}{2} \int_{1}^{\zeta} \frac{\sigma \zeta}{(\omega+\sigma \zeta)^{2} \omega^{2}} \int_{1}^{\omega}\left(\frac{\eta}{1+\sigma \eta}\right)^{2} \mathrm{~d} \eta \mathrm{~d} \omega \\
& -\frac{\sigma(1+\sigma)^{2}}{2} \int_{1}^{\zeta} \frac{\zeta}{(1+\sigma \omega)(\omega+\sigma \zeta)^{2}} \mathrm{~d} \omega \\
& -\left.\frac{\sigma(1+\sigma)}{2 \zeta^{2}} \int_{1}^{\zeta}\left(\frac{\eta}{1+\sigma \eta}\right)^{2} \mathrm{~d} \eta\right|_{\zeta=e^{(1+\sigma) \xi / 2}} \\
= & -\sigma(1+\sigma)^{2} \int_{1}^{\zeta} \frac{1}{(\omega+\sigma \zeta)^{2} \omega} \int_{1}^{\omega}\left(\frac{\eta}{1+\sigma \eta}\right)^{2} \mathrm{~d} \eta \mathrm{~d} \omega \\
& -\left.\frac{\sigma(1+\sigma)}{\zeta^{2}} \int_{1}^{\zeta}\left(\frac{\eta}{1+\sigma \eta}\right)^{2} \mathrm{~d} \eta\right|_{\zeta=e^{(1+\sigma) \xi / 2}}, \quad \xi \in[0, \lambda d] \tag{4.52}
\end{align*}
$$

where for the last equation again integration by parts has been used. Note that the r.h.s. of (4.52) can be evaluated by using the dilogarithm function

$$
\operatorname{Li}_{2}(z):=-\int_{0}^{z} \frac{\log (1-\omega)}{\omega} \mathrm{d} \omega
$$

Summarizing, from (4.46), (4.52), (4.51), (4.48), and (4.49) we find the following representation for the LST of $V(\tau)$.

Theorem 4.1 Let the stability condition $\varrho<2$ for the $M / G I / 2-P S$ system, where the service time fulfills (4.45), be satisfied. Then for $s \in \mathbb{R}_{+}$and $\tau \in[0, d]$ the LST of $V(\tau)$ is given by

$$
\begin{gather*}
E\left[e^{-s V(\tau)}\right]=\frac{1-\varrho / 2}{1+\varrho / 2}\left(-2 \sigma(1+\sigma)^{2} \int_{1}^{\zeta} \frac{1}{(\omega+\sigma \zeta)^{2} \omega} \int_{1}^{\omega}\left(\frac{\eta}{1+\sigma \eta}\right)^{2} \mathrm{~d} \eta \mathrm{~d} \omega\right. \\
\quad-\frac{\sigma(1+\sigma)}{\zeta^{2}} \int_{1}^{\zeta}\left(\frac{\eta}{1+\sigma \eta}\right)^{2} \mathrm{~d} \eta-\frac{1+\sigma}{1+\sigma \zeta} \\
\left.\quad+\frac{2(1+\sigma)^{2}}{(1-\varrho / 2)(1+\sigma)^{2}+\sigma \log (\zeta)+\sigma^{2}(\zeta-1)}\right)\left.\right|_{\sigma=s / \lambda, \zeta=e^{(\lambda+s) \tau / 2}} \\
\tau \in[0, d] . \tag{4.53}
\end{gather*}
$$

Note that Theorem 4.1 also provides the LST of $V(\tau), \tau \in\left[0, m_{S}\right]$, and in particular the LST of $V=V\left(m_{S}\right)$ in $M / D / 2-P S$ for $d=m_{S}$.

Taking the $k$ th derivative with respect to $s$ at $s=0$ on both sides of (4.53) yields the $k$ th moment of $V(\tau)$ for $\tau \in[0, d]$. In particular, we find the following simple expression for the variance of $V(\tau)$ after tedious algebra.

Corollary 4.1 Let the stability condition $\varrho<2$ for the $M / G I / 2-P S$ system, where the service time fulfills (4.45), be satisfied. Then for $\tau \in[0, d]$ the variance of $V(\tau)$ is given by

$$
\begin{align*}
& \operatorname{var}(V(\tau))=\frac{1}{\lambda^{2}}\left(\frac{2 \varrho \xi^{2}}{(1+\varrho / 2)^{2}(1-\varrho / 2)^{2}}-\frac{4\left(e^{\xi}-1-\xi\right)}{(1+\varrho / 2)(1-\varrho / 2)}\right. \\
& \left.\quad+\frac{2}{9} \frac{1-\varrho / 2}{1+\varrho / 2}\left((12 \xi-10) e^{\xi}+9+e^{-2 \xi}\right)\right)\left.\right|_{\xi=\lambda \tau / 2}, \quad \tau \in[0, d] \tag{4.54}
\end{align*}
$$

Note that Corollary 4.1 also provides the variances of $V(\tau), \tau \in\left[0, m_{S}\right]$, and of $V=V\left(m_{S}\right)$ in $M / D / 2-P S$ for $d=m_{S}$, cf. Table 3.1 for $r=2$.

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